

A New Compilation Path: From Python/ NumPy to OpenCL

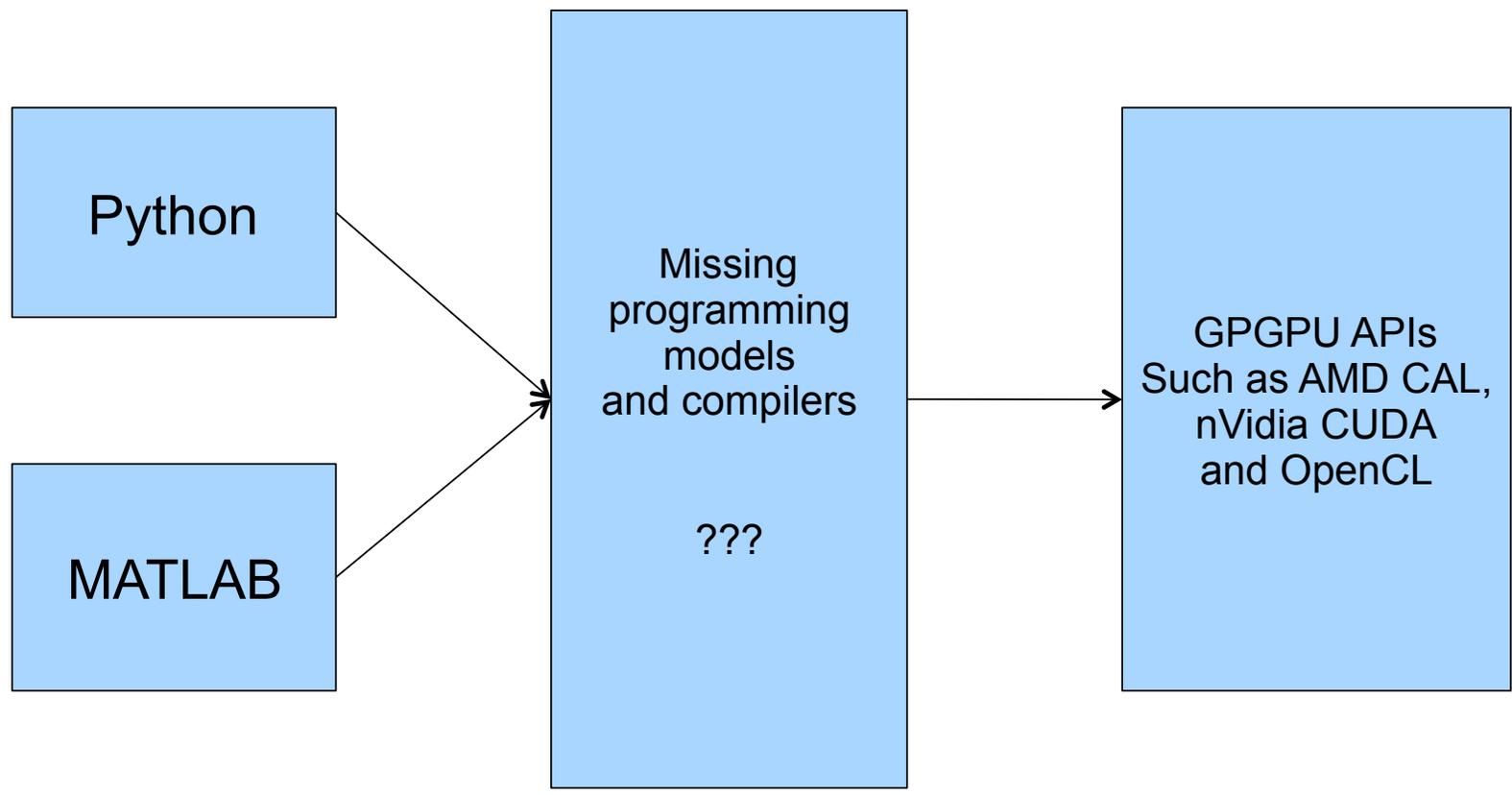


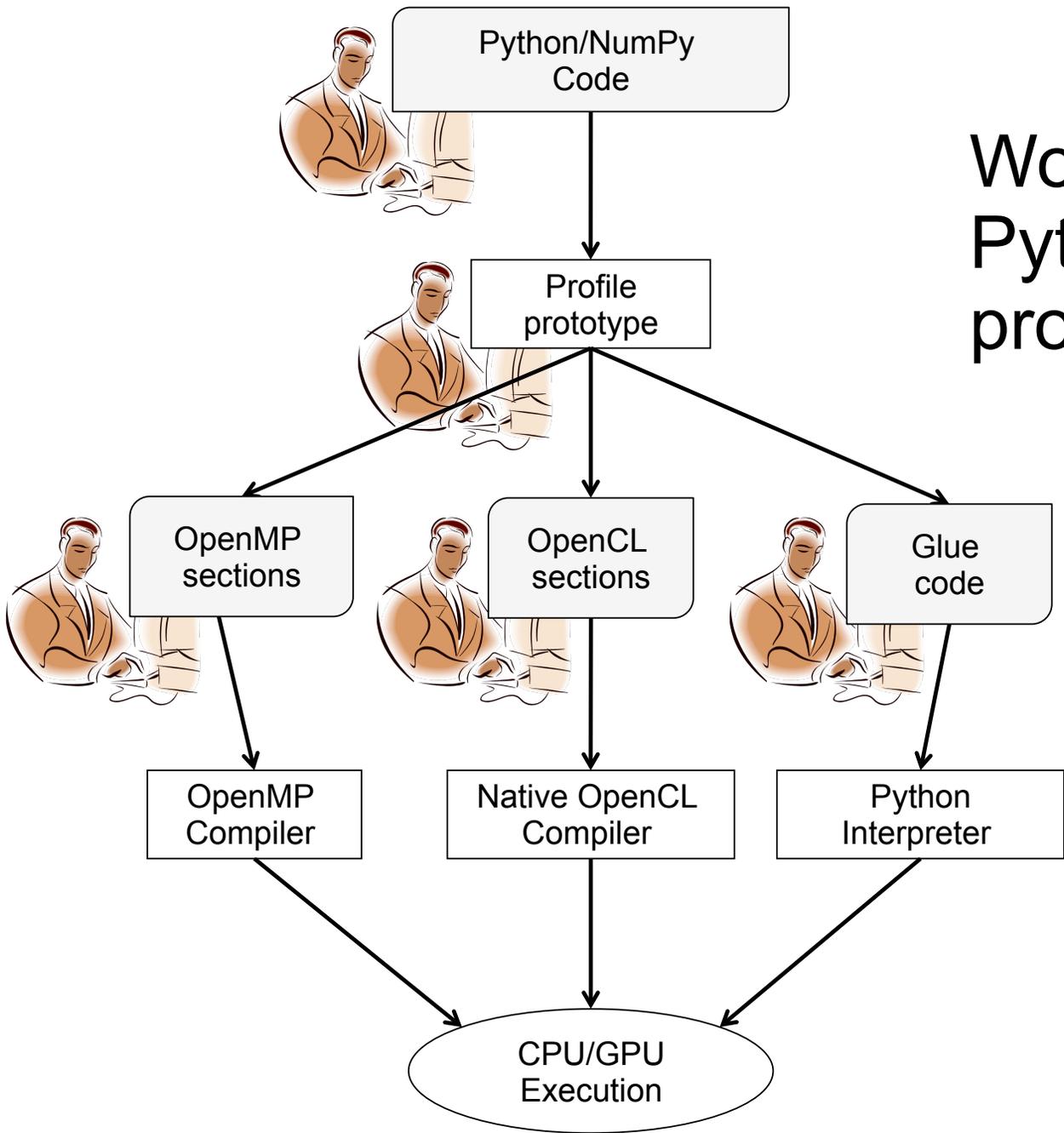
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Special Purpose Computation on
Graphics Processing Units

GPGPU from high-level languages?





Workflow for a Python programmer

unPython:

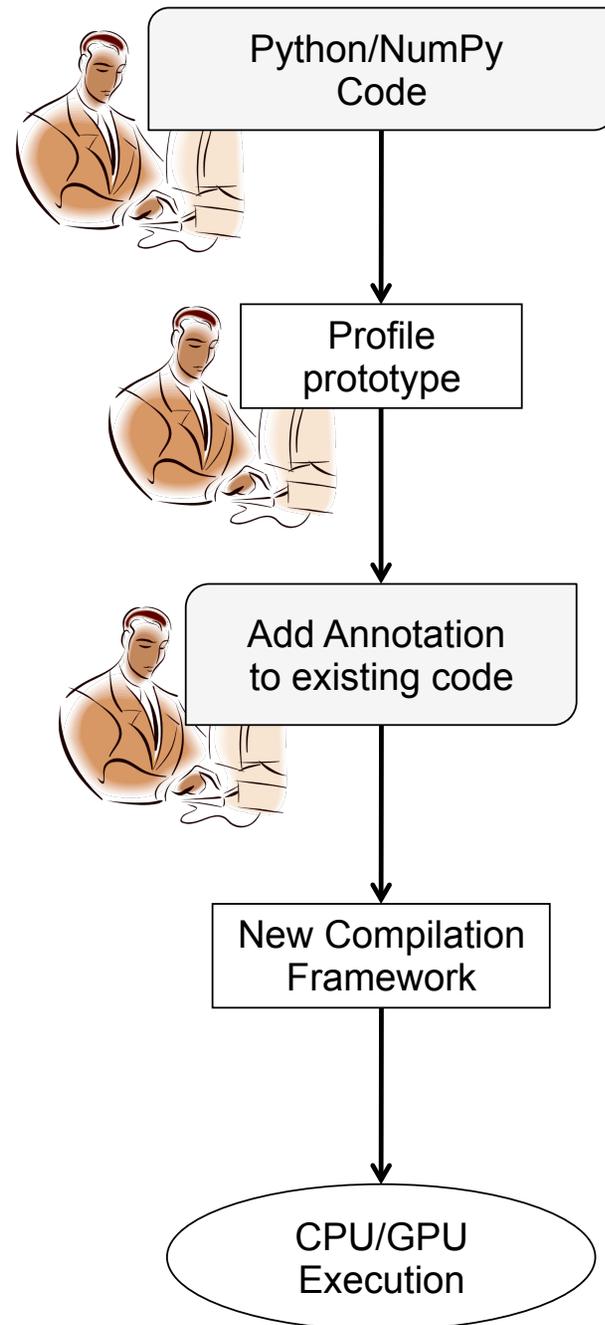
```
1  for  $i_1$  in prange( $u_1$ ):
2      for  $i_2$  in prange( $u_2$ ):
3          ...
4          for  $i_m$  in prange( $u_m$ ):
5              for  $i_{m+1}$  in range( $u_{m+1}$ ):
6                  .
7                  .
8                  for  $i_d$  in range( $u_d$ )
9                      #loop body
```

Figure 5.1: Loop nests considered for array access analysis

Python/NumPy to CPU/GPU

- A special parallel loop annotation to accelerate a particular loop nest using the GPU
- Programming model based on shared memory model similar to OpenMP
- Compiler attempts to identify data accessed inside the loop
- Copies all relevant data to GPU
- Generates GPU code (using CAL API)
- Executes in GPU and copies data back
- If analysis fails, fall back to generated C/C++ code

Workflow using unPython



Data Transfer to GPU

To transfer data to GPU execution:

- Identify set of memory locations accessed

- Find the amount of GPU memory required

- Translate CPU memory addresses to GPU addresses

Hard to do ahead-of-time, not enough information

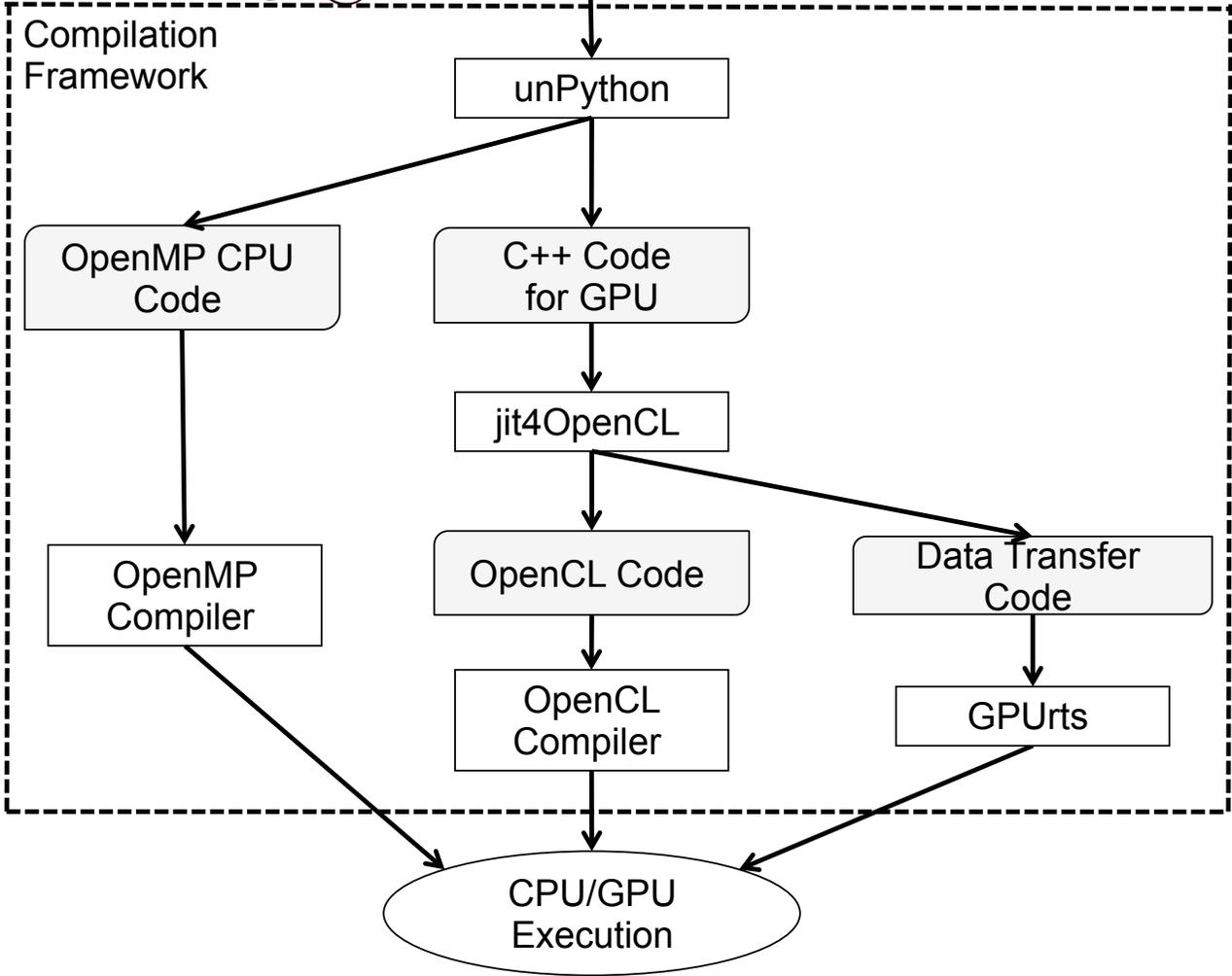
We introduce a new just-in-time compiler named
“jit4OpenCL”

jit4OpenCL

- jit4OpenCL is a specialized compiler:
 - Only to handle parallel loop-nests
 - Generated OpenCL code targets GPU execution
- For loops marked parallel, unPython inserts a call to jit4OpenCL to compile the loop
- jit4OpenCL performs data access analysis and attempts to generate OpenCL code
- If jit4OpenCL fails, then execution falls back to OpenMP code generated by unPython
- If jit4OpenCL succeeds, it generates OpenCL code and code for all relevant data transfers



Python/Numpy
Code with Annotations



Problem:

Given a loop nest:

Which memory locations are accessed?

Do these locations fit in the GPU memory?

If not, how to make them fit?

Key Insights:

Use Linear Memory Access Descriptors to represent referenced locations

Restrict to loops with constant-stride accesses

Further restrict to loops in which each reference is to a unique memory location.

Tile loop nest to make it fit in the GPU memory.

Array access analysis in jit4OpenCL

- identifies the set of memory locations accessed by array references in a loop nest
- uses a new array access analysis algorithm based on Linear Memory Access Descriptors (LMADs) [PaekHoeflingPaduaTOPLAS02]
- LMADs:
 - represent memory-address expressions directly
 - require subscripts to be affine expressions of loop counters

Constant-Stride LMADs (CSLMADs)

- Given a loop nest with d nested loops:
 - The lower bound of all loops is 0
 - Upper bounds are affine functions of the loop indices of the outer loops
 - The indices and the strides of the loops are:

$$\vec{i} = (i_1, i_2; \dots, i_d)$$

$$\vec{s} = (s_1, s_2; \dots, s_d)$$

CSLMADs (cont.)

- The set of memory locations accessed by a CSLMAD are given by:

$$M = f(\vec{i}) = b + \sum_{k=1}^d s_k \times i_k$$

Base Strides Indices

CSLMADs (example)

```
char A[P][80]
```

```
1: for(u=0; u<100; u++)  
2:   for(v=0; v<v+5; v++)  
3:     ... = A[u+v+1][2*u+2];
```

$$f(i,j) = \&A[0][0] + 80 \times (u+v+1) + (2 \times u + 2)$$

$$= \&A[0][0] + 82 \times u + 80 \times v + 82$$

$$= (\&A[0][0] + 82) + 82 \times u + 80 \times v$$

The diagram shows the expression $(\&A[0][0] + 82) + 82 \times u + 80 \times v$ with three components identified by brackets and labels below:

- A bracket under $(\&A[0][0] + 82)$ is labeled b .
- A vertical line under $82 \times u$ is labeled s_1 .
- A vertical line under $80 \times v$ is labeled s_2 .

$$M = f(\vec{i}) = b + \sum_{k=1}^d s_k \times i_k$$

Restricted CSLMADs

CSLMAD:

$$M = f(\vec{i}) = b + \sum_{k=1}^d s_k \times i_k$$

Additional constraint for RCSLMAD:

$$s_{r_k} \geq s_{r_d} - 1 + \sum_{j=k+1}^d u_{r_j} \times s_{r_j}$$

In an
RSCLMAD
each reference
is to a unique
memory
location.

r_k : position of stride s_{r_k} in a stride list sorted in decreasing order.

s_{r_d} : smallest stride

s_{r_1} : largest stride

CSLMAD × RCSLMAD (examples)

CSLMAD:

$$M = 3u + v, u < 10, v < 4$$

$$(u, v) = (0, 3) \rightarrow M = 3$$

$$(u, v) = (1, 0) \rightarrow M = 3$$

RCSLMAD:

$$M = 4u + v, u < 10, v < 4$$

$$(u, v) = (0, 3) \rightarrow M = 3$$

$$(u, v) = (1, 0) \rightarrow M = 4$$

There are no two pairs (u, v) that map to the same location.

jit4OpenCL Code Generation

- For OpenCL compiler has to perform on-chip memory allocations.
- jit4OpenCL introduces new memory compactation techniques.
- Transform reference addresses to new space
- Match # of accesses with # of thread blocks (currently uses 16×16 blocks)

Data Transfers

- OpenCL API requires initialization of device memory objects with specific sizes
- Jit4OpenCL:
 - Configures the OpenCL grid
 - Sorts RCSLMAD elements
 - Use memory-address mapping for memory transfers
 - Matches RCSLMAD elements to threads
 - Decides which elements will be in local memory for each thread.
 - Redirects Array Access References

Evaluation - Benchmarks

CP: Columbic Potential (planar grid)

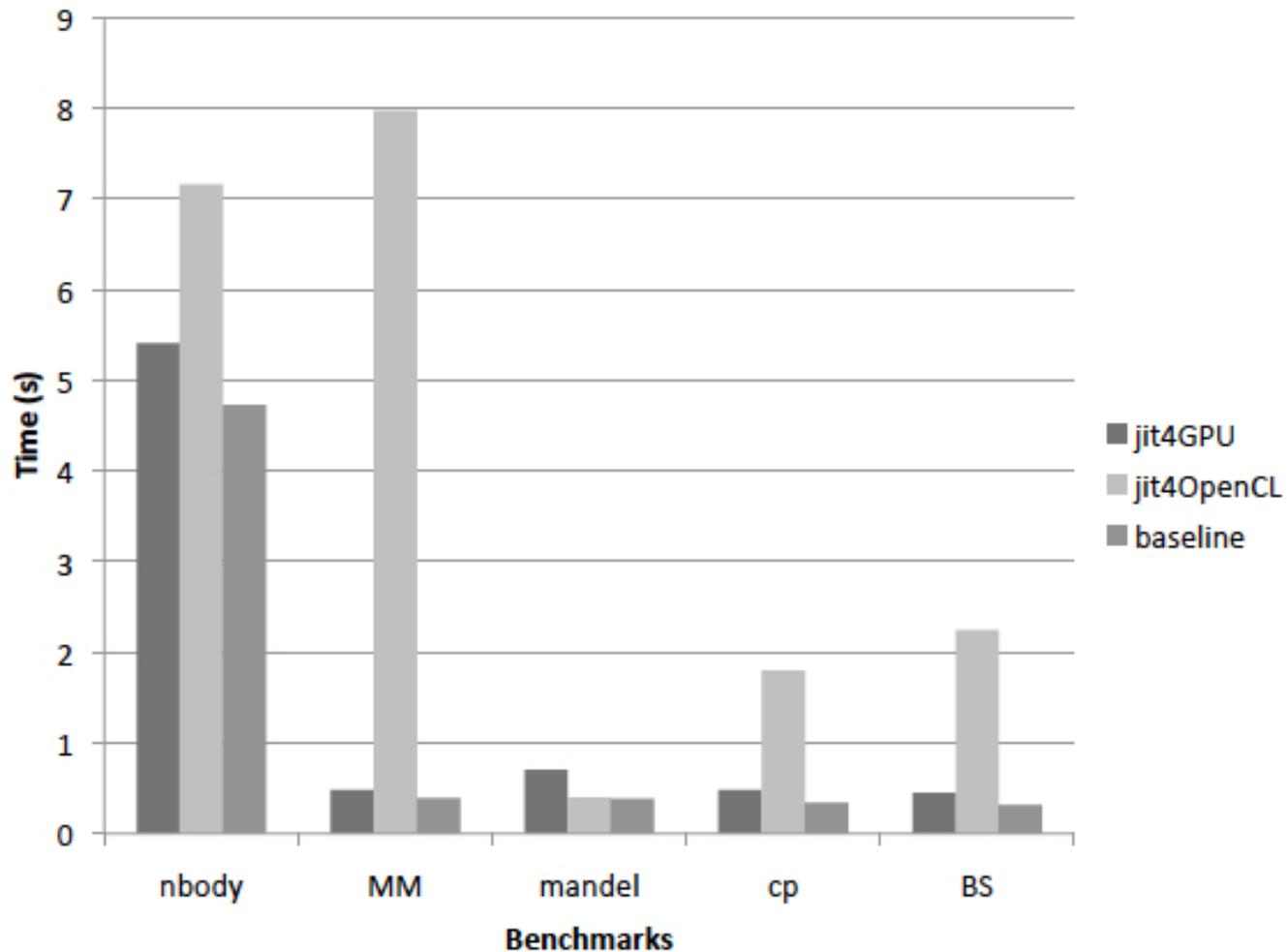
NB: N-Body simulation (a kernel only)

BS: Black-Sholes formulas

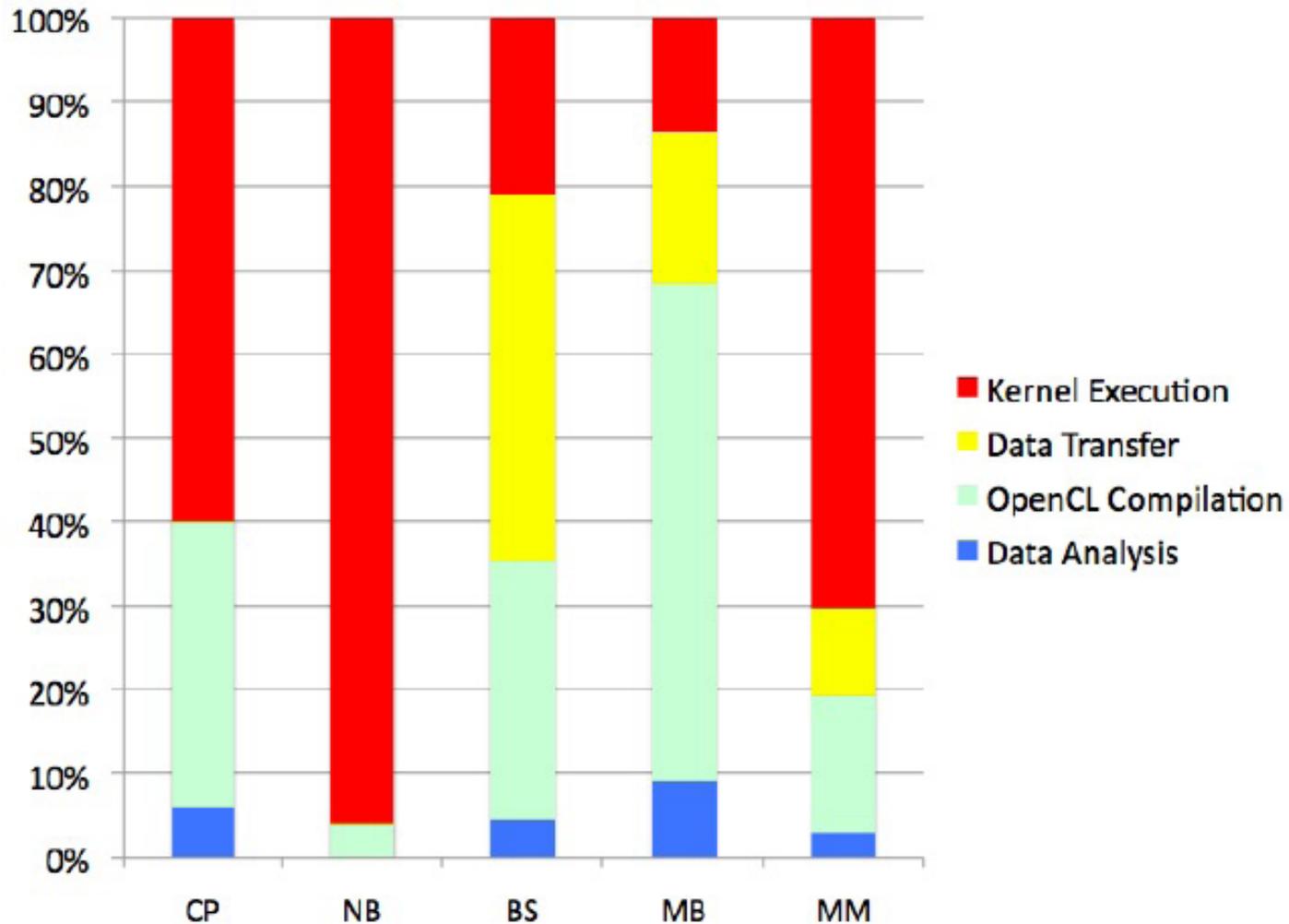
MB: approximation of Madelbrot set

MM: Matrix multiplication

Comparison with jit4GPU and Hand-written OpenCL code (on AMD Radeon 5850)



Where is time spent? (jit4OpenCL on NVidia GTX260)



Take-Away Points

- OpenCL portability comes with a performance cost
- Data transfers in OpenCL are more constrained and might be limiting speed.
- Jit4OpenCL is a quick way to test a Python/NumPy application in many platforms.
- Increased memory bandwidth in GPUs and improvement of native OpenCL compilers is likely to help with performance.