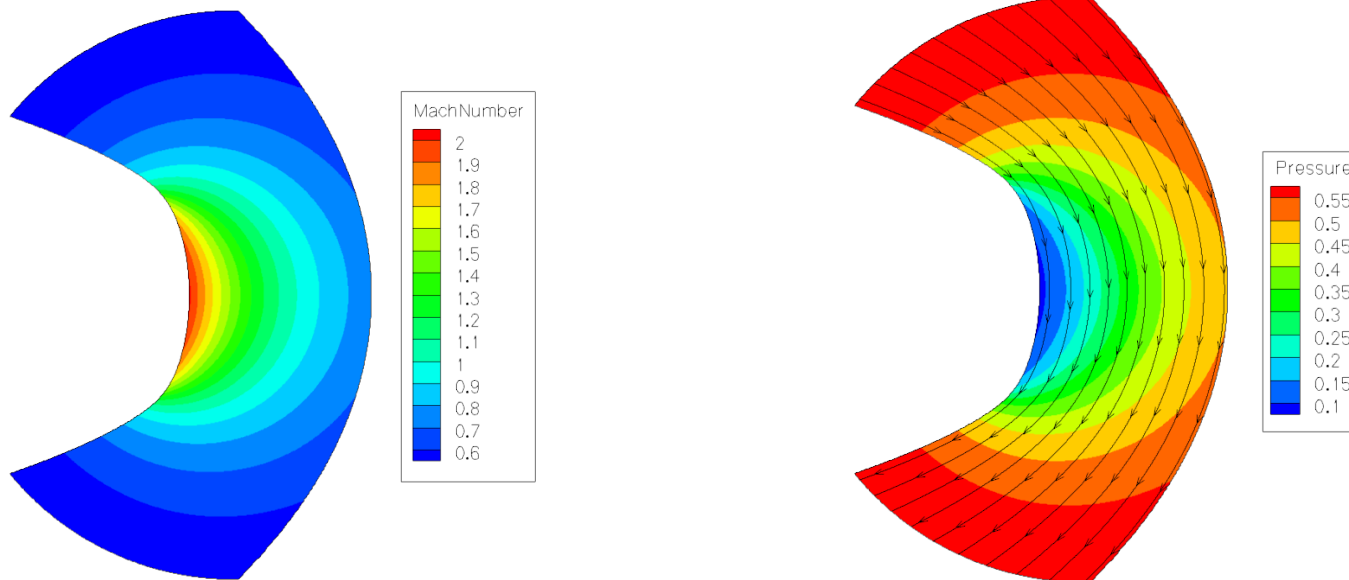


Test case C1.2: Ringleb flow Summary

Edwin van der Weide, University of Twente, the Netherlands

e.t.a.vanderweide@utwente.nl



2nd International Workshop on High Order CFD Methods

May 27-28, 2013

Cologne, Germany

Contributions

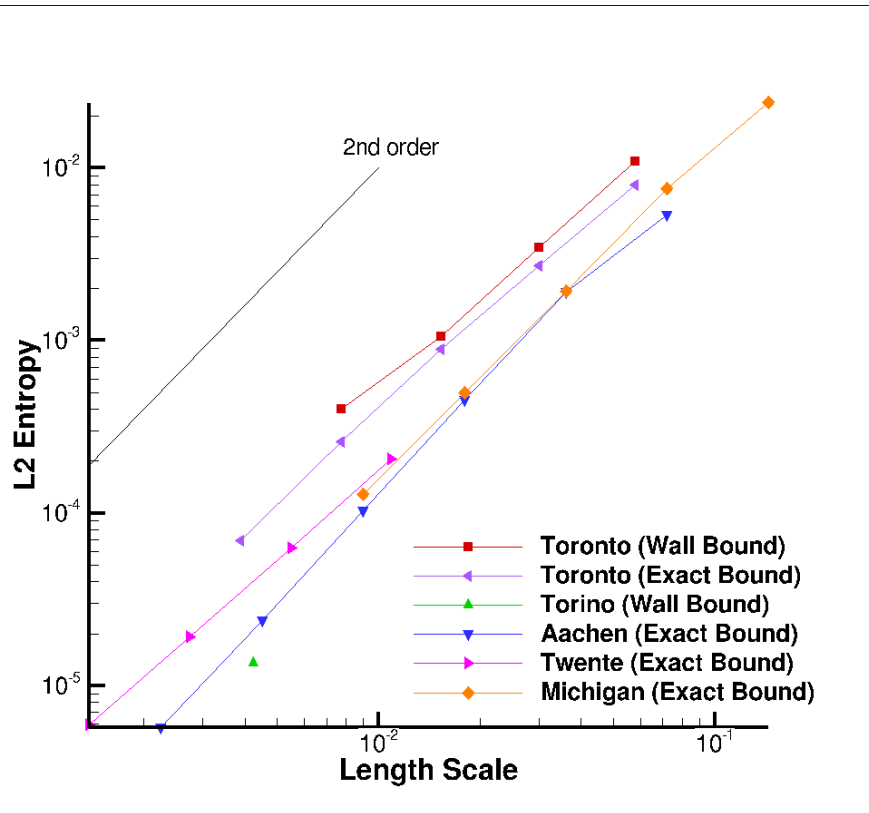
- University of Toronto
 - SBP/SAT FD, Newton-Krylov
- Politecnico Torino
 - DG, explicit Runge Kutta
- RWTH Aachen
 - DG, Newton-Krylov
- University of Twente / University of Bergen
 - SBP/SAT FD, Newton-Krylov
- University of Michigan
 - DG, Newton-Krylov
 - Adaption

Observations

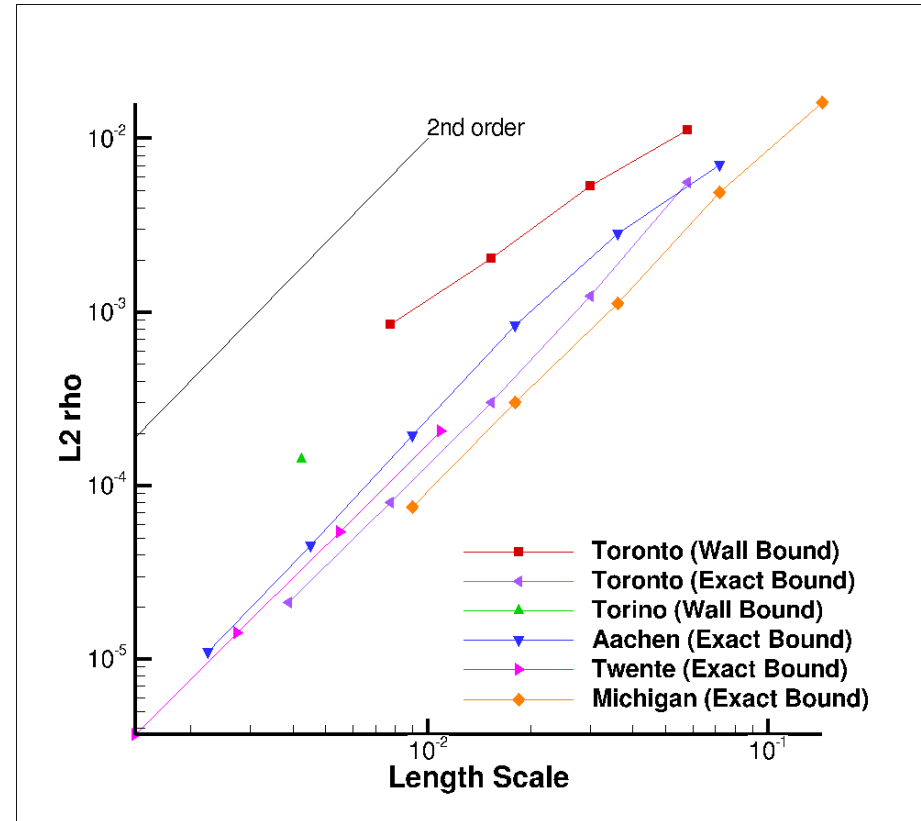
- Correct representation of the wall is crucial
 - 2nd order FD schemes fail with standard metric
 - Solutions, FD
 - Penalize against exact solution (Twente, Toronto)
 - Use higher order representation (Toronto)
 - Solutions, DG
 - Use exact solution (Aachen, Michigan)
 - Use relatively fine grids (Torino)
- Newton-Krylov most popular iterative solver

Accuracy, $p = 1$ (2nd order)

Entropy

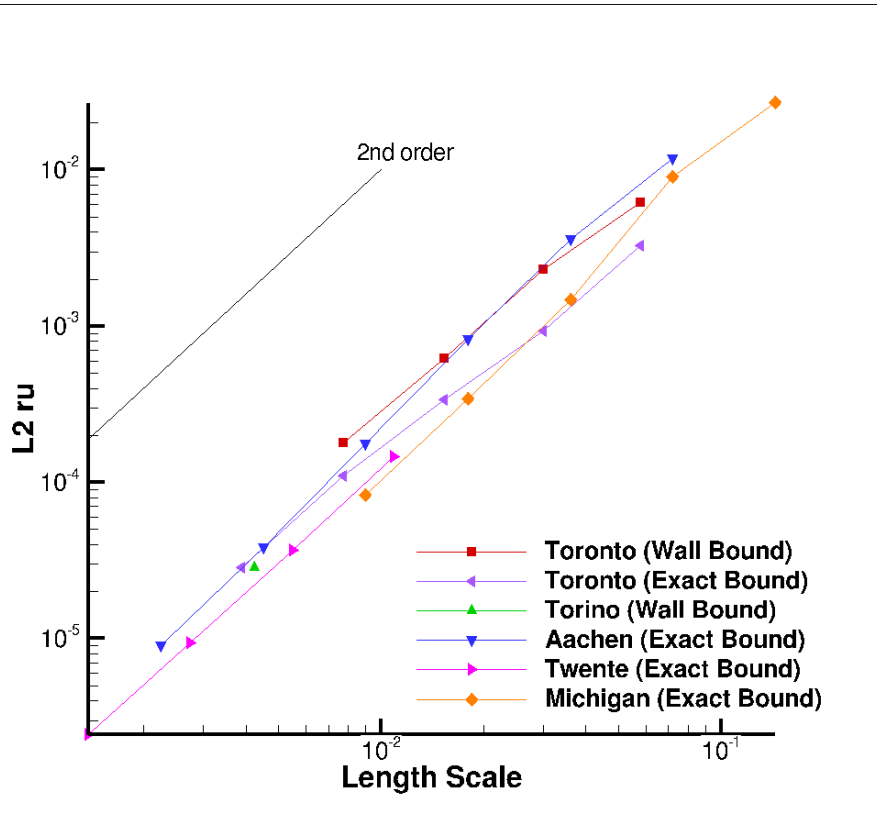


Density

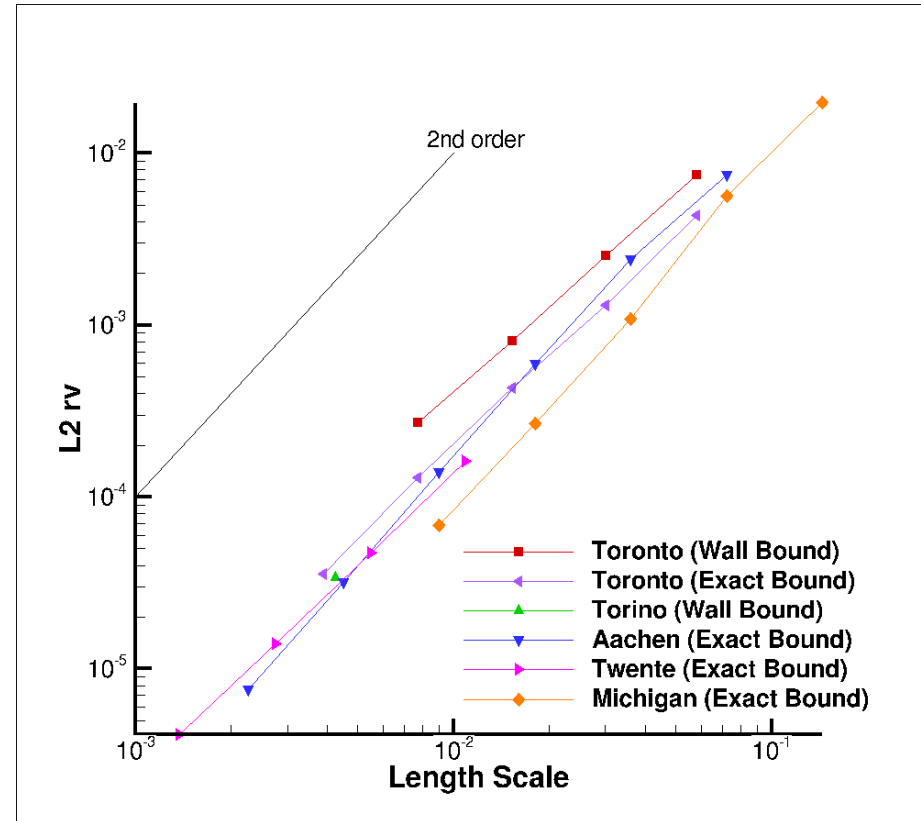


Accuracy, $p = 1$ (2nd order)

X-Momentum

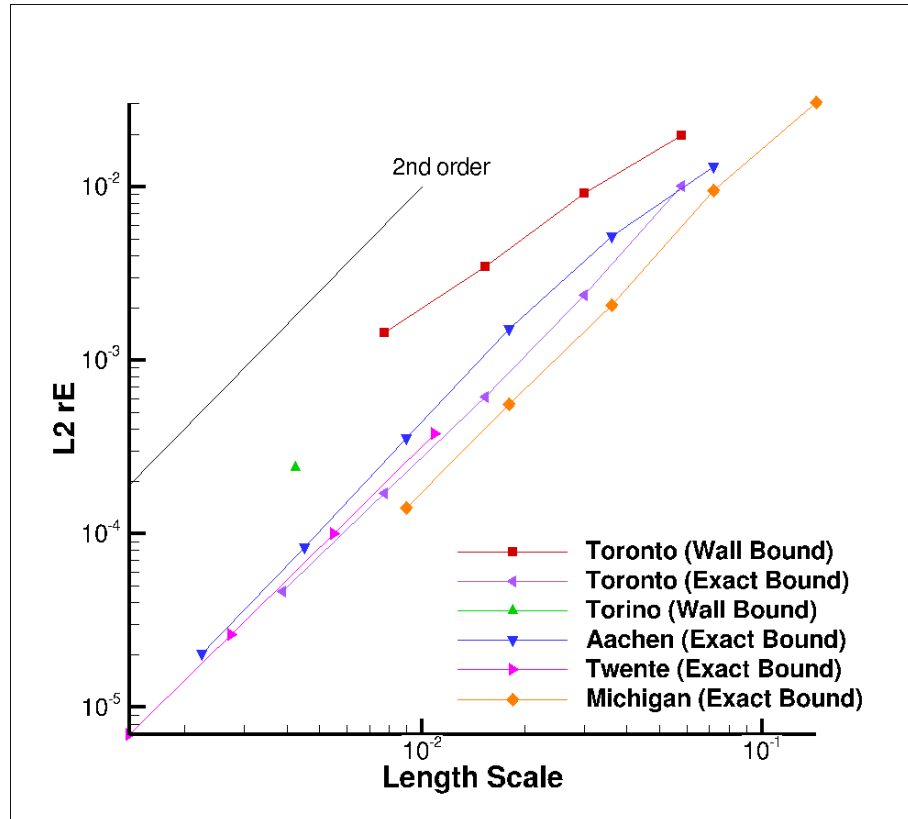


Y-Momentum



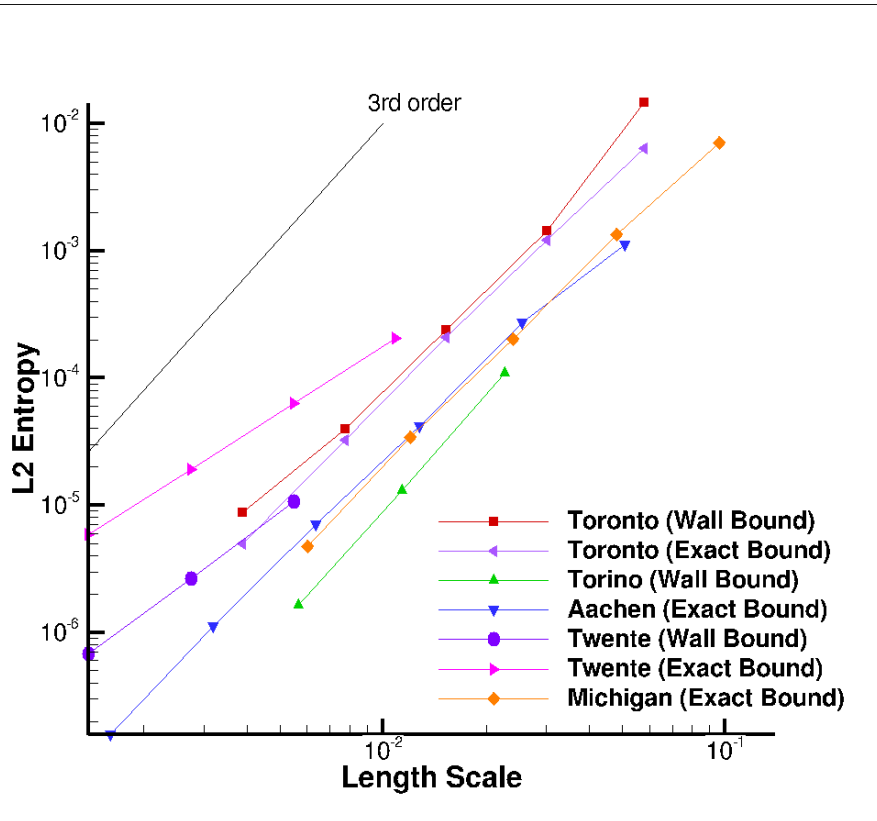
Accuracy, $p = 1$ (2nd order)

Energy

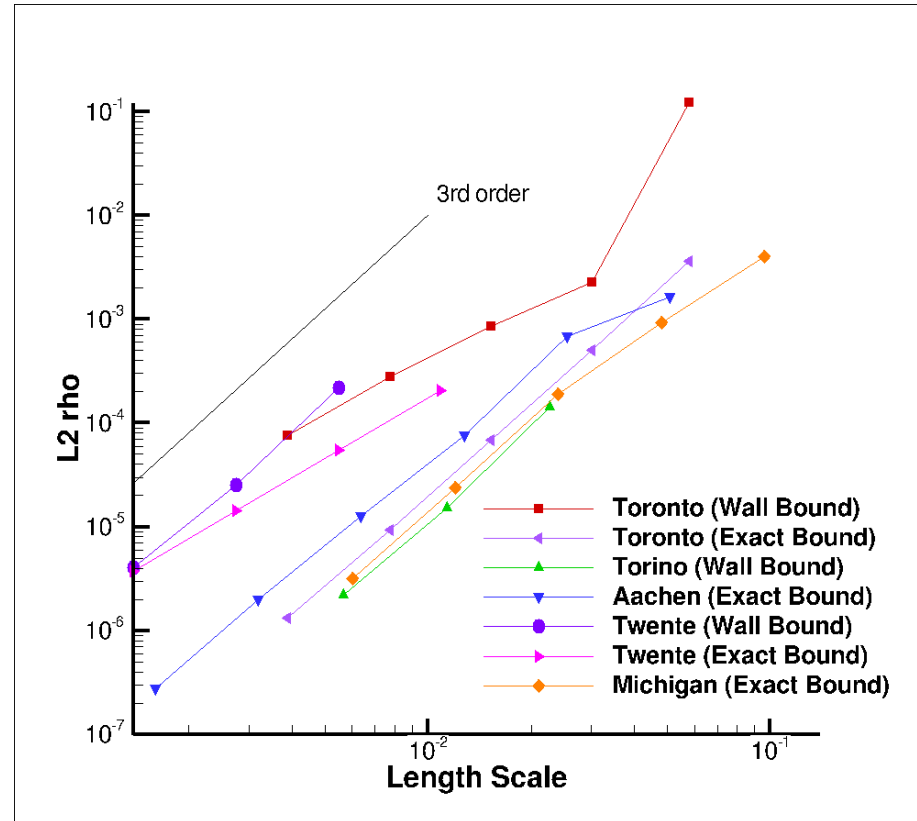


Accuracy, $p = 2$ (3rd order)

Entropy

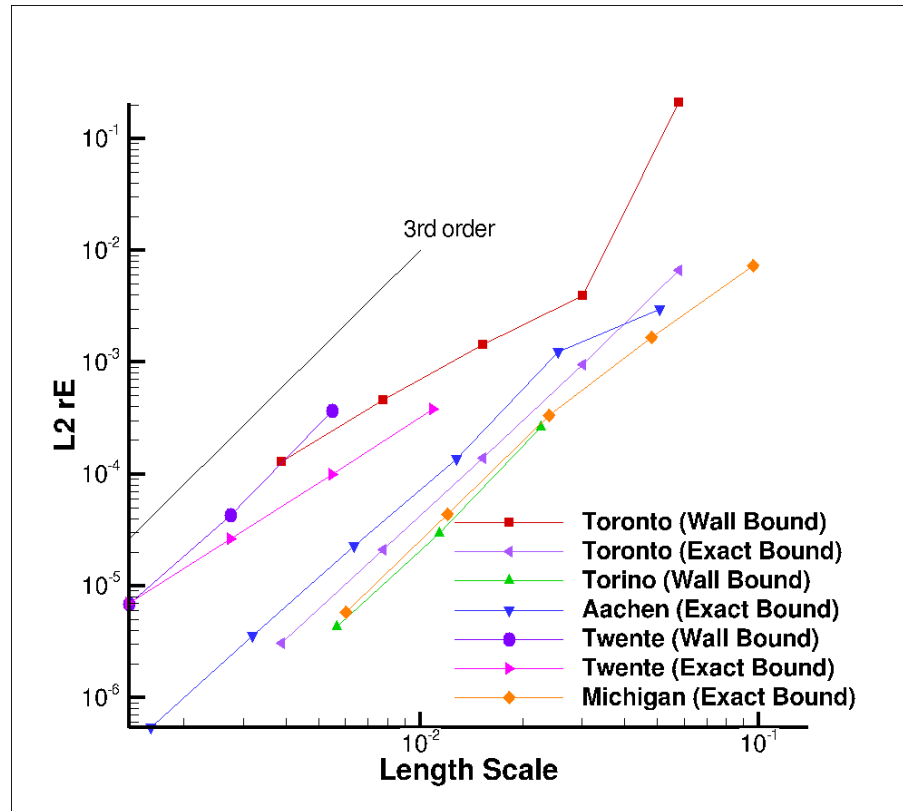


Density



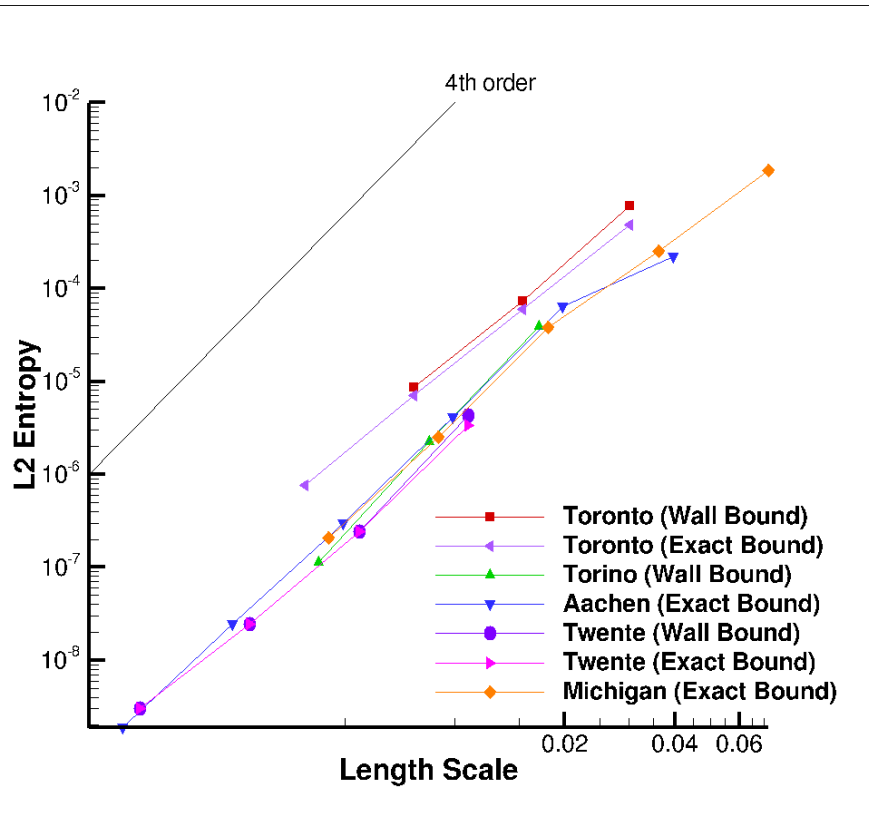
Accuracy, $p = 2$ (3rd order)

Energy

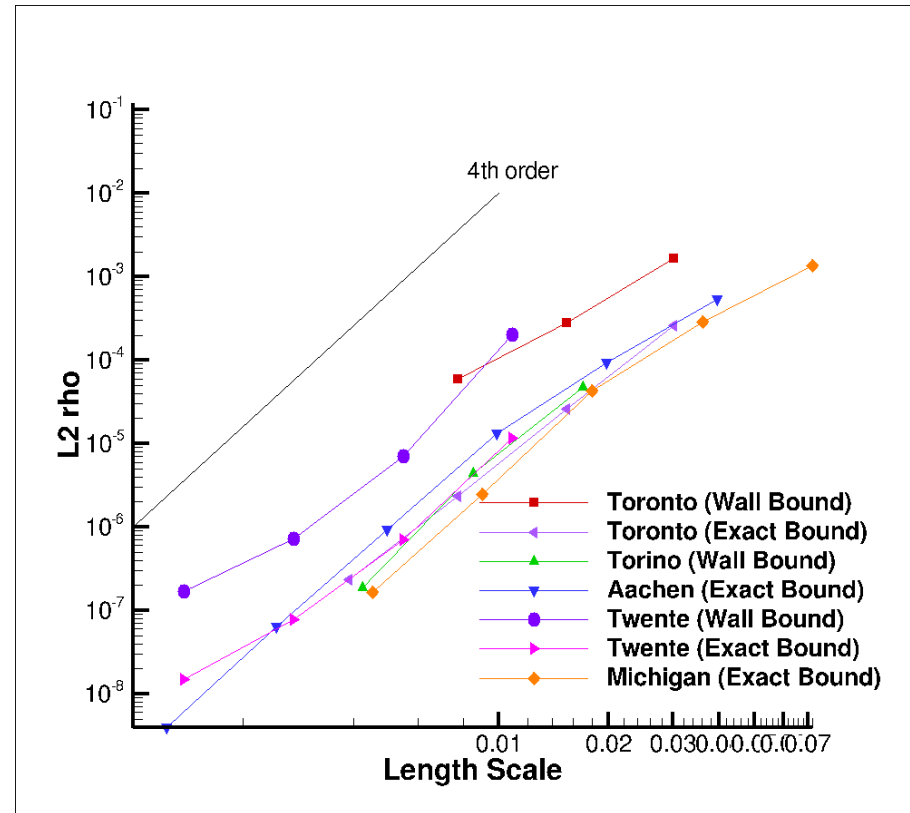


Accuracy, $p = 3$ (4th order)

Entropy

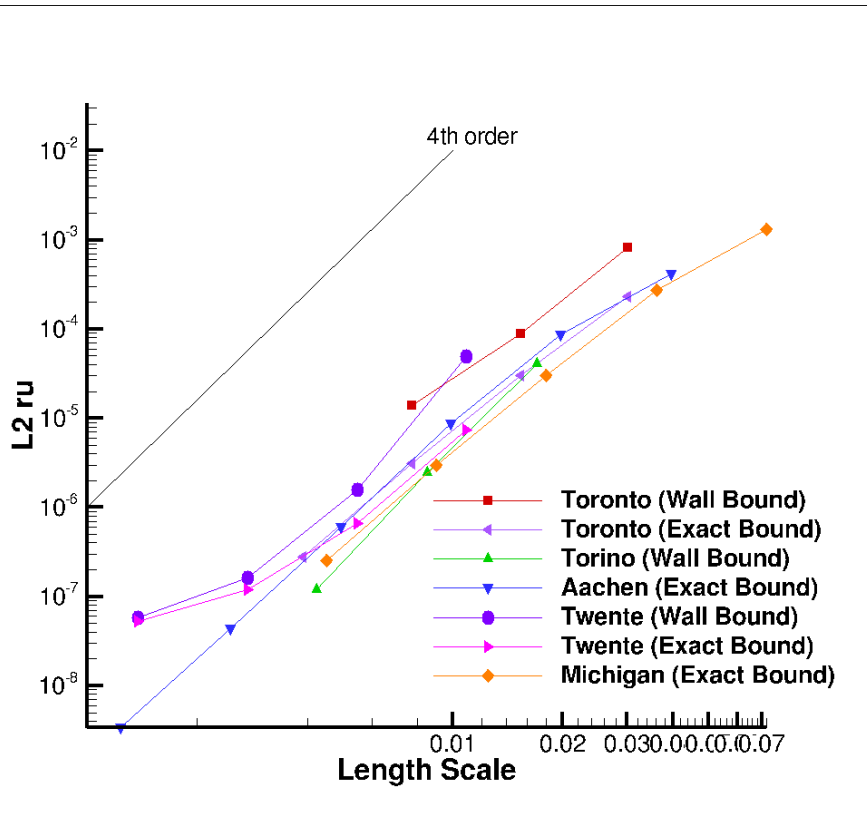


Density

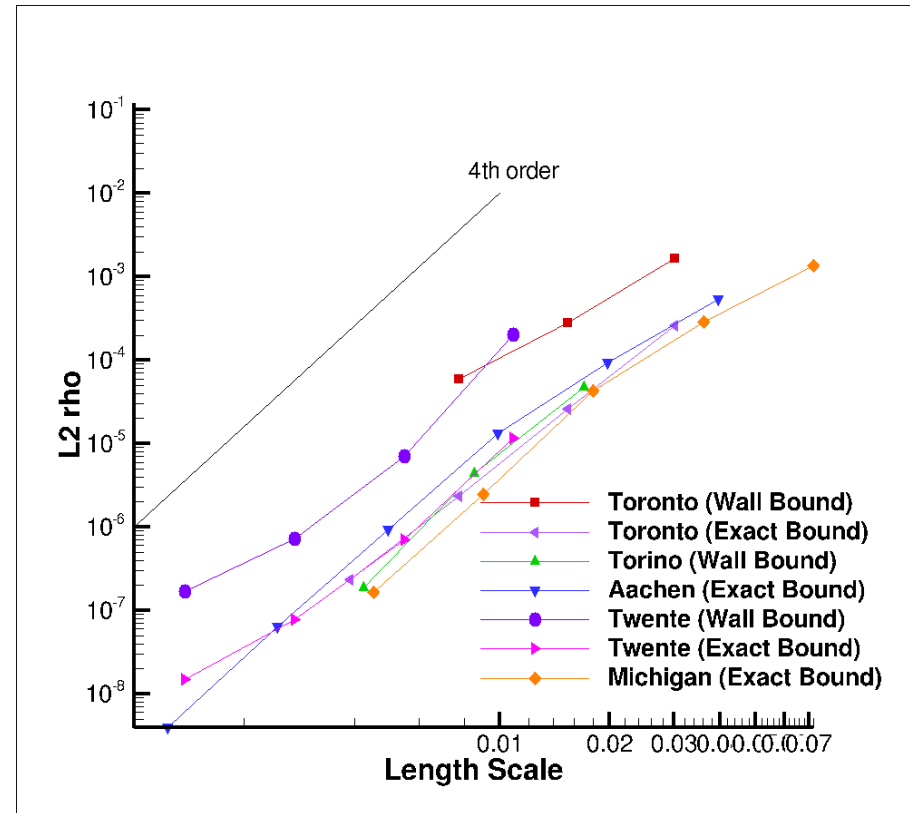


Accuracy, $p = 3$ (4th order)

X-Momentum

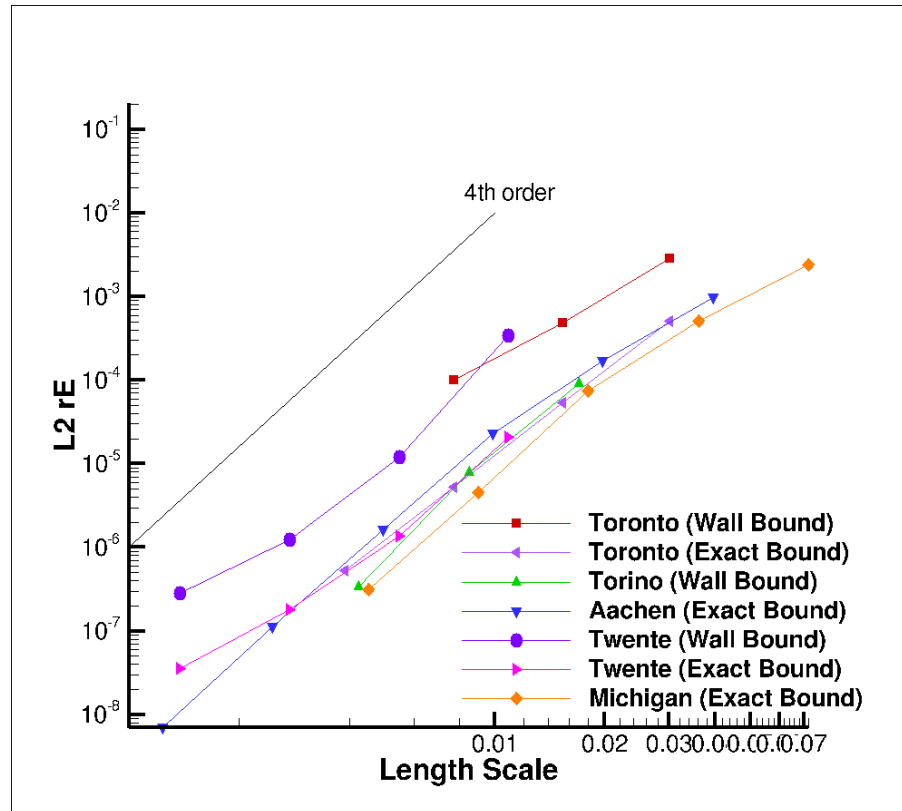


Y-Momentum



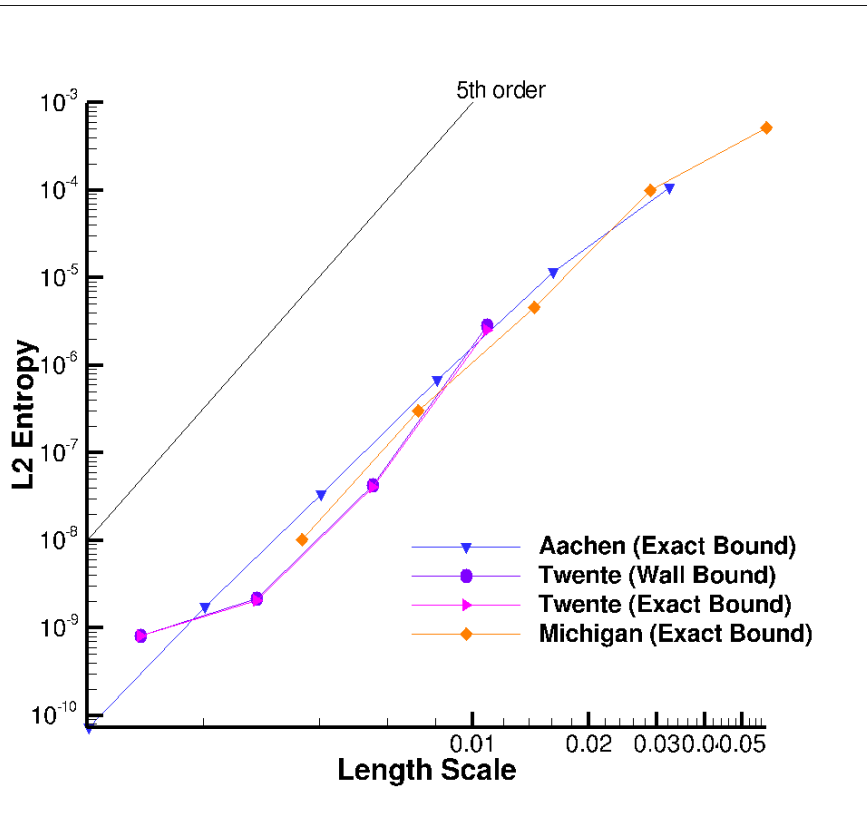
Accuracy, $p = 3$ (4th order)

Energy

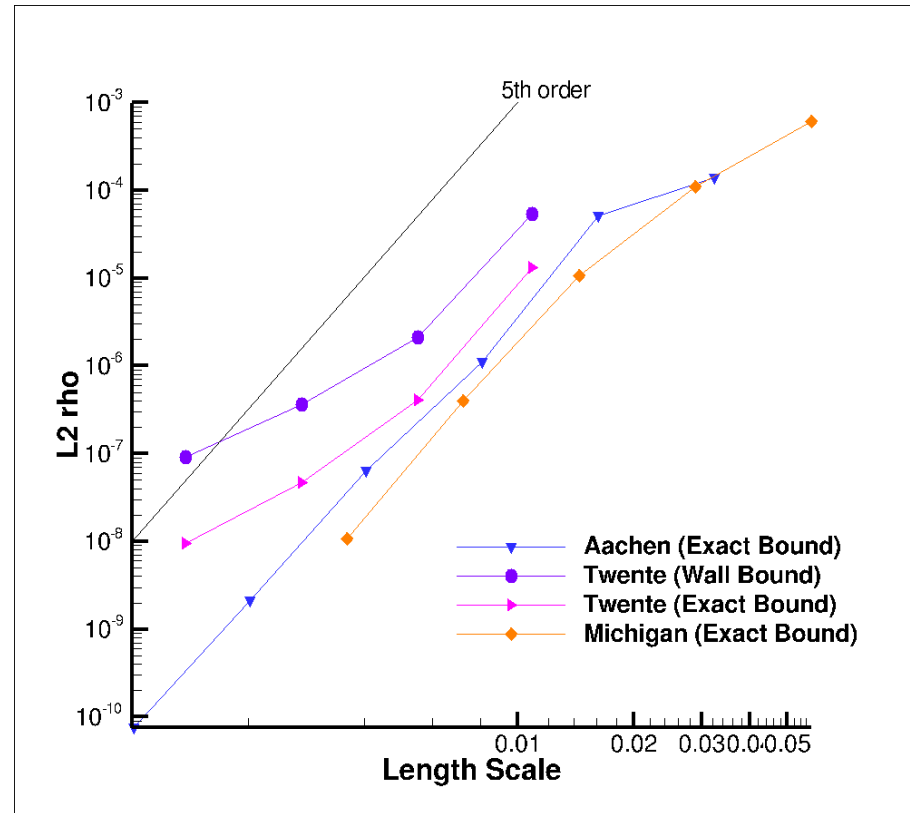


Accuracy, $p = 4$ (5th order)

Entropy

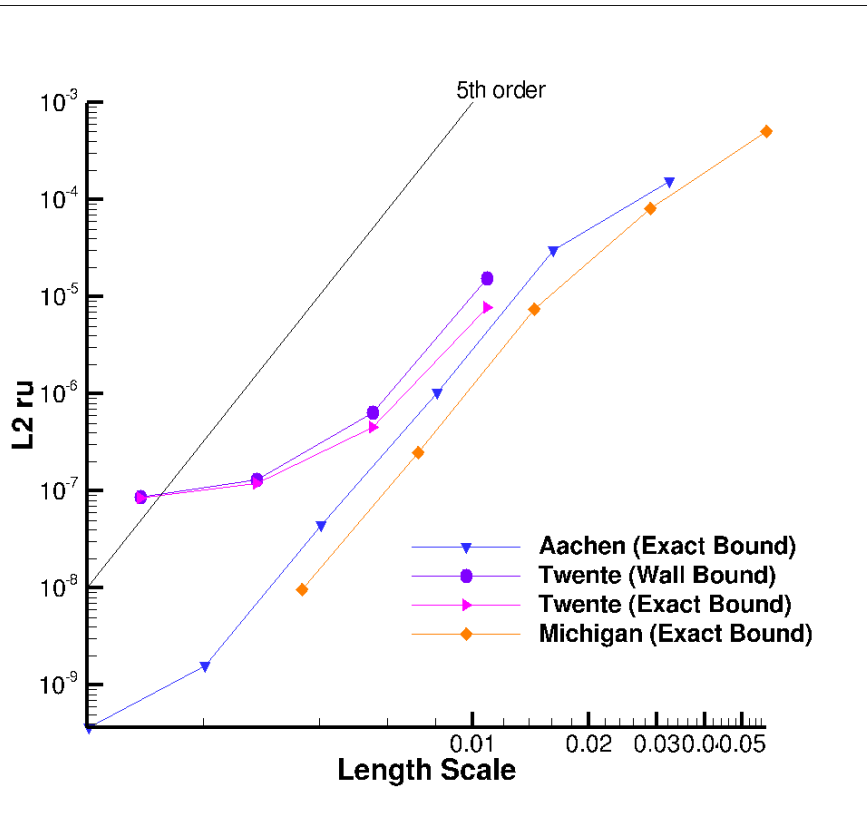


Density

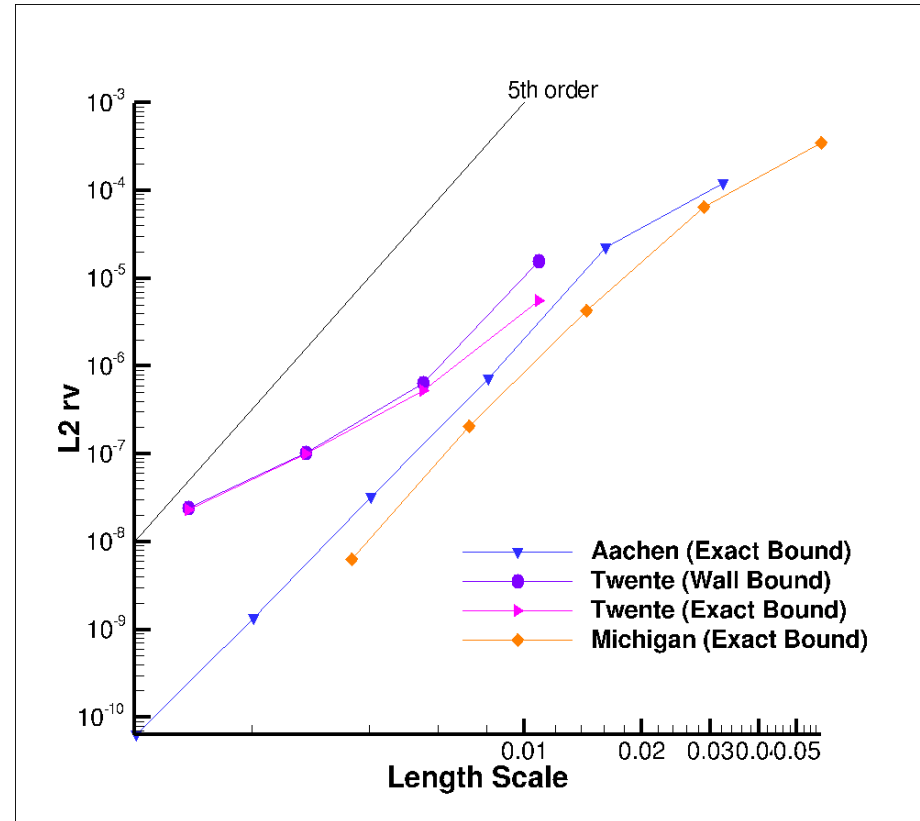


Accuracy, $p = 4$ (5th order)

X-Momentum

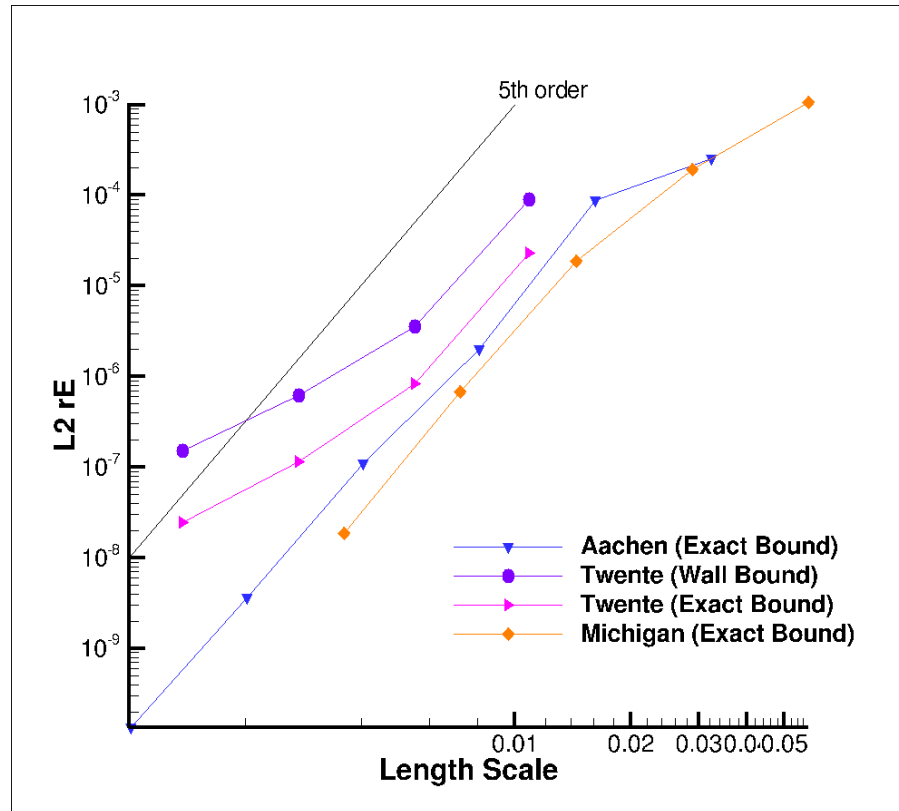


Y-Momentum



Accuracy, $p = 4$ (5th order)

Energy



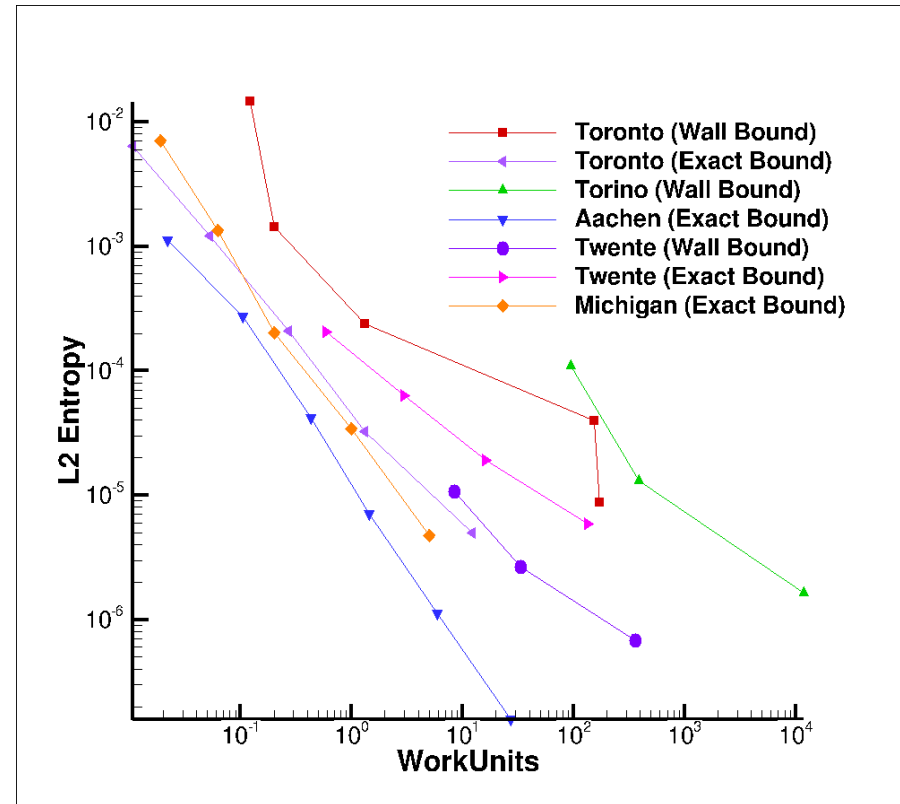
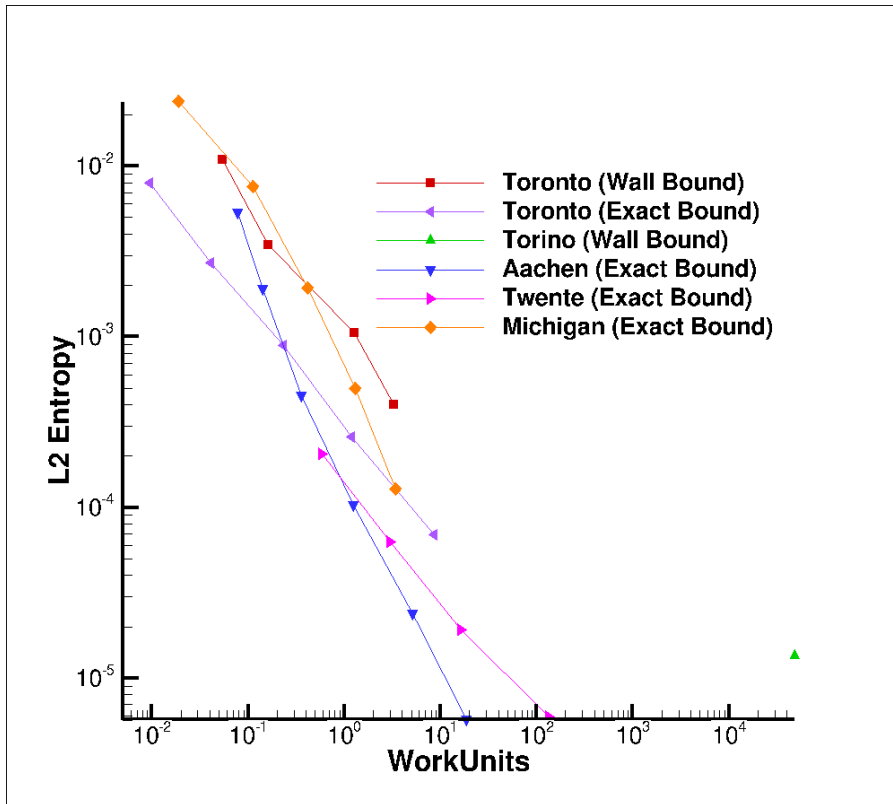
Efficiency

- All codes are research codes
 - Most likely not fully optimized. Could easily be a factor of 2
- Which boundary conditions are used
 - Inviscid walls vs. exact solution can make a big difference
- Initial solution is exact solution
 - Finer grids and/or high order schemes are close => Efficiency cannot be fairly compared
- Memory usage not taken into account
 - Newton Krylov uses a lot of memory
 - Not a problem in 2D, but possibly in 3D
- Most efficient algorithm seems Newton Krylov
 - Preconditioned GMRES as iterative solver

Efficiency, entropy error

$p = 1, 2^{\text{nd}}$ order

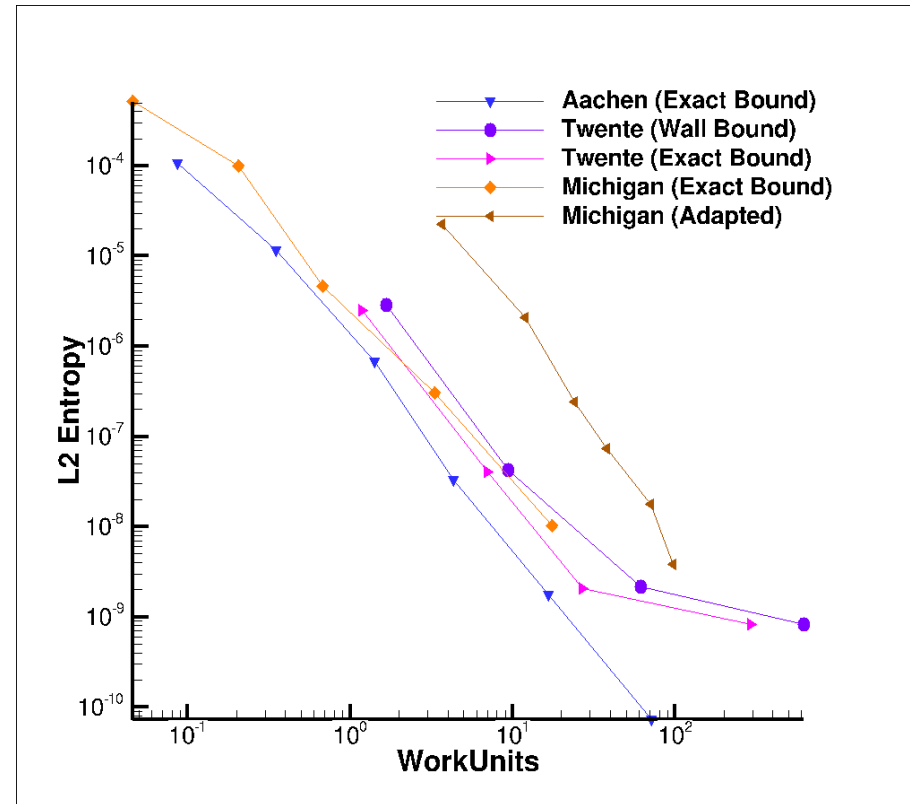
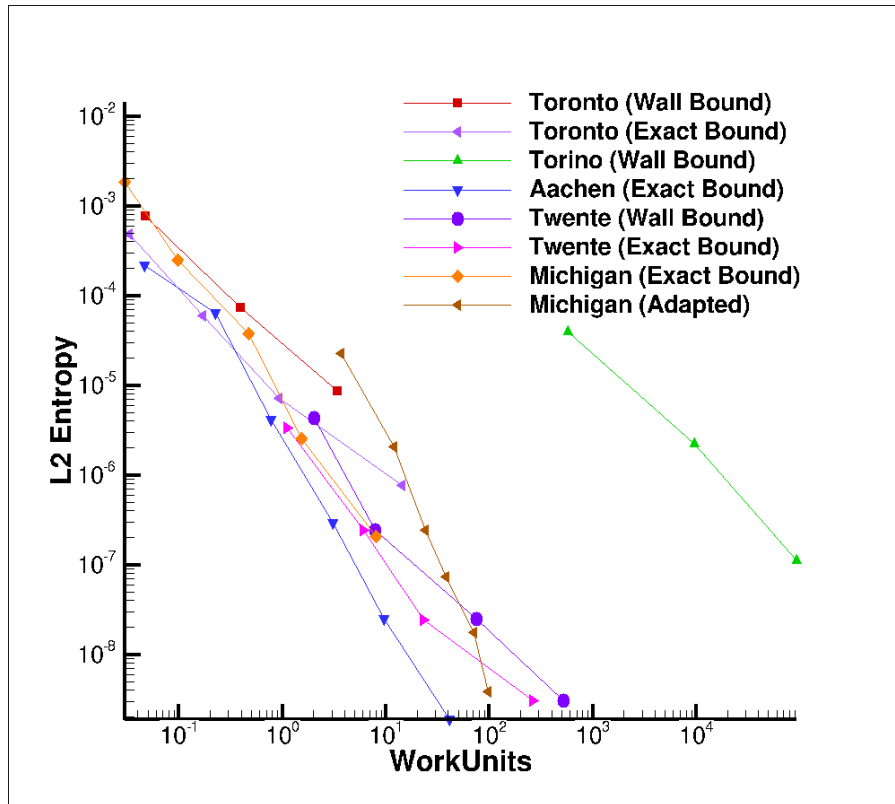
$p = 2, 3^{\text{rd}}$ order



Efficiency, entropy error

$p = 3, 4^{\text{th}}$ order

$p = 4, 5^{\text{th}}$ order



Conclusions

- Accurate wall description is crucial when wall BC's are used
 - Alternative: BC's based on exact solution
- All DG methods show design accuracy
 - Question is what happens on very fine grids when wall BC's are used
- FD methods show design accuracy for 2nd and 3rd order schemes and 4th and 5th order schemes on not too fine grids
- Accuracy of 4th and 5th order FD scheme (Twente) on very fine grids degrade
 - Cause: Under investigation
- Both DG and FD can be made very efficient using Newton Krylov methods
- Adaption does not seem to pay off for this case (in work units)
 - It most likely will for a more complicated case