



AUTOSAR Adaptive Platform – a trustable software framework for connected and autonomous driving

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AUTOSAR Spokesperson

Symposium Testen - Automatisiertes und Vernetztes Fahren
Braunschweig, September 4th 2018

BMW
GROUP



BOSCH



DAIMLER



TOYOTA

VOLKSWAGEN
AKTIENGESELLSCHAFT

Topics

› AUTOSAR Introduction

› Challenges and Use Cases

› Developing the Adaptive Platform

› Roadmap, Achievements



(AUTomotive Open System ARchitecture)

is a worldwide development partnership of car manufacturers, suppliers and other companies from the electronics, semiconductor and software industry.

AUTOSAR – Core Partners and Partners



9 Core Partners



AUTOSAR



53 Premium Partners



38 Development Partners



127 Associate Partners
21 Attendees

Why do we rely on standards?

Share

efforts on non-differentiating parts

Compete

on innovative functions with increased design flexibility

Reduce

costs on overall software development

Simplify

software and system integration

Distribute

development among suppliers

Enable

cooperation

Create

markets and enable new business models

What makes standardization successful?

Yesterday

Paper standards with specifications only

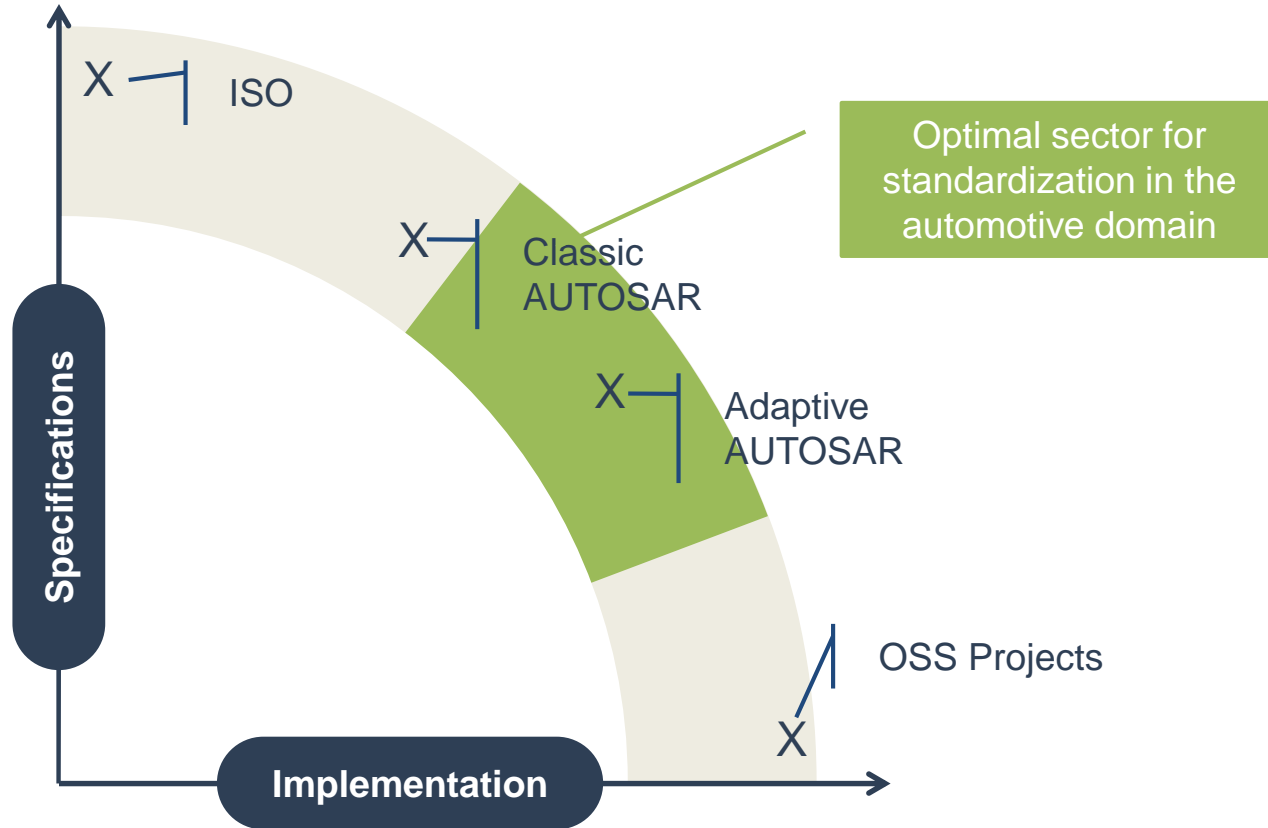
Introduction and functional overview	
Acronyms and abbreviations	1
Related documentation	1
Constraints and assumptions	1
Dependencies to other modules	1
Requirements traceability	2
Functional specification	3
API specification	6
8.1 Imported types	6
8.2 Type definitions	6
8.3 Function definitions	6
8.4 Call-back notifications	7
8.5 Scheduled functions	7
8.6 Expected Interfaces	7
Sequence diagrams	8
0 Configuration specification	8

Today

Joint implementation
based on specifications

```
21713  // ...
21714  var watchExpr = attr.ngSwitch ? attr.ngSwitch : null;
21715  selectedTranscludes = [];
21716  selectedElements = [];
21717  previousElements = [];
21718  selectedScopes = [];
21719
21720  scope.$watch(watchExpr, function ngSwitchMatchAction(value) {
21721    var i, ii;
21722    for (i = 0, ii = previousElements.length; i < ii; ++i) {
21723      previousElements[i].remove();
21724    }
21725    previousElements.length = 0;
21726
21727    for (i = 0, ii = selectedScopes.length; i < ii; ++i) {
21728      var selected = selectedElements[i];
21729      selectedScopes[i].$destroy();
21730      previousElements[i] = selected;
21731      $animate.leave(selected, function() {
21732        previousElements.splice(i, 1);
21733      });
21734    }
21735
21736    selectedElements.length = 0;
21737    selectedScopes.length = 0;
21738
21739    if ((selectedTranscludes = ngSwitchController.transclude("ngSwitch" + value)) != null) {
21740      scope.$eval(attr.change);
21741      forEach(selectedTranscludes, function(selectedTransclude) {
21742        var selectedScope = scope.$new();
21743        selectedScopes.push(selectedScope);
21744        selectedTransclude.transclude(selectedScope);
21745      });
21746    }
21747  });
```

Automotive software standardization at its best



Advantages of AUTOSAR's licensing model

AUTOSAR

Licensing

- all contributed IP of any partner is royalty free for all partners
- Source code and specifications are covered

Liability

- Minimized for all partners

Open Source Software

Licensing

- Only contributed IP of specific partner is royalty free



Open Innovation Network

- All complements licensing for Linux

Liability

- Excluded

Key factors to make AUTOSAR Adaptive Platform a success



Short development cycles



Frontloading of validation



Precision and quality of the standard

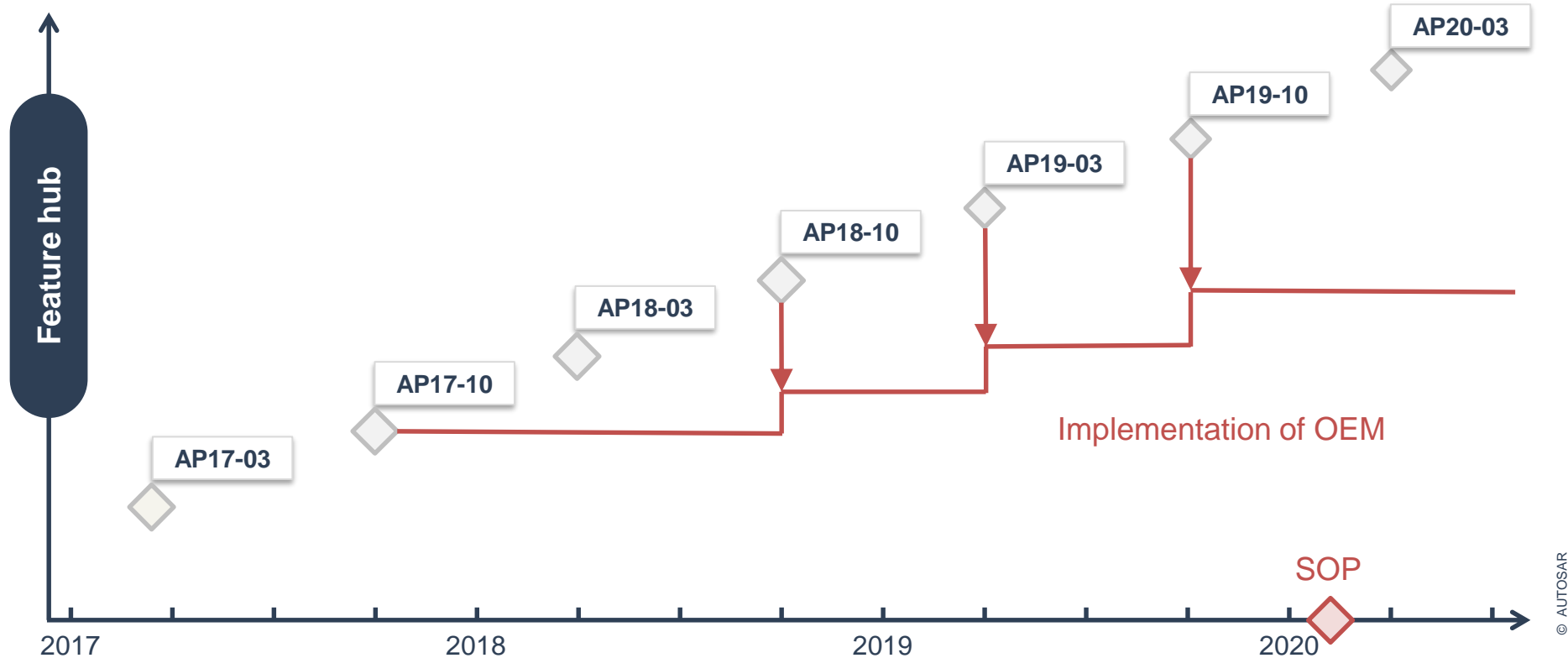


Early availability of exemplary implementation



Interoperability and increased quality

Flexible implementation of AUTOSAR Adaptive Platform



AUTOSAR Adaptive Platform

Making the series product

AUTOSAR AP
Specification and
Source Code



Validation
Maintenance
Documentation
HW Adaption
Configuration
Liability
Testing



Total effort
to create
a product

Besides all technical advantages

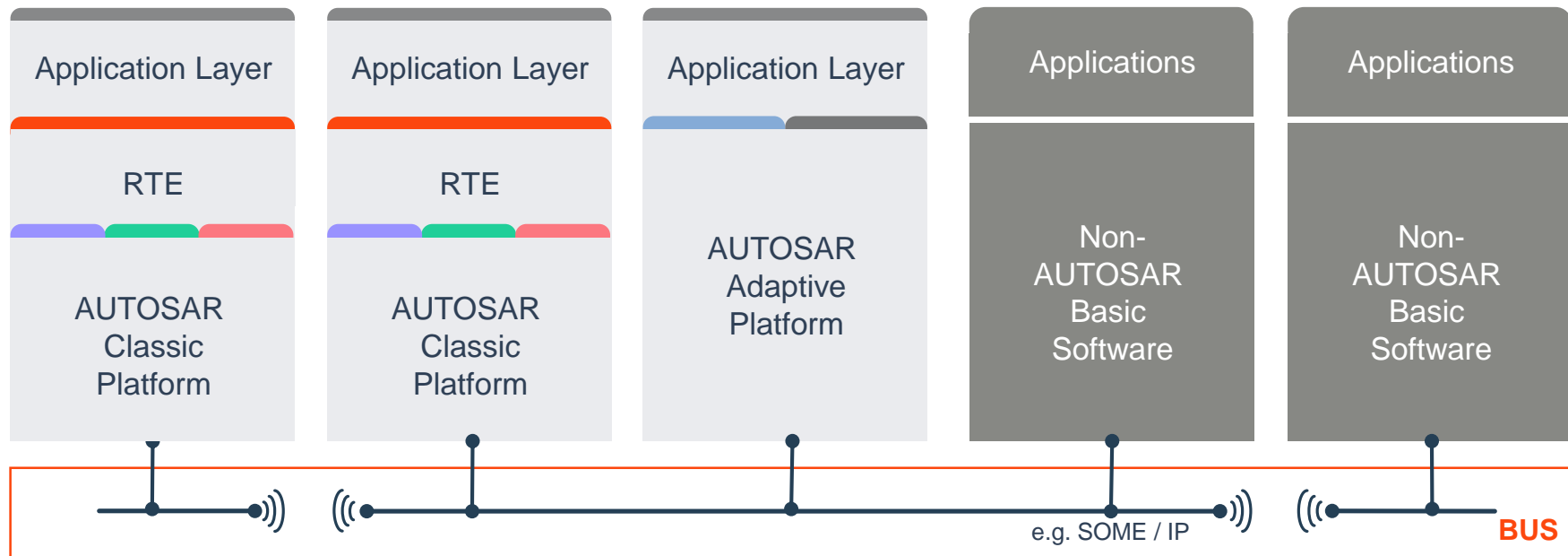


AUTOSAR partners form a strong community

Collaboration, exchange of experiences, discussions...

...with companies you would never have met!

AUTOSAR standardizes two software platforms – Classic and Adaptive



Common Bus Interface Specification

Topics

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Game changer for AUTOSAR – selected main drivers

Main drivers for new automotive software systems have been determined.



➤ Highly automated driving

Game changer for AUTOSAR – selected main drivers

Main drivers for new automotive software systems have been determined.



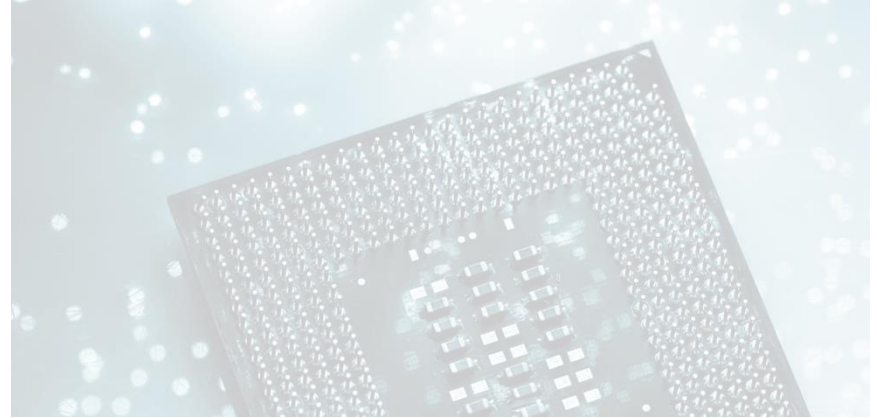
- › Car-2-X applications
- › Internet of Things and cloud services

Game changer for AUTOSAR – selected main drivers

Main drivers for new automotive software systems have been determined.

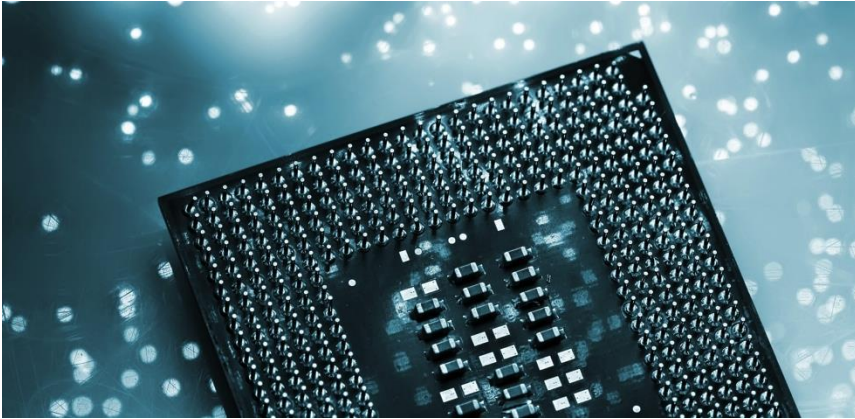


➤ Increasing data rates



Game changer for AUTOSAR – selected main drivers

Main drivers for new automotive software systems have been determined.



- New processor technologies

Autonomous vehicle: It's all about trust !



The basis of autonomous driving is **Trustability**.

Trustability means **Reliability** at any instance of operation. Reliability is based on **Availability, Safety and Security**.

(Basic Picture: Volkswagen Concept Car Sedric, Geneva Car Salon 2018)

Timeline to full automation

2017

2020

2023

2026

Level 3 automated driving - Conditional automation:

Trustworthy software platform enables developers by safety and security measures to develop onboard software for automated driving.

Level 4 highly automated driving:

E/E Systems cope with all situations automatically in defined use cases. SW platform provides the framework to cope with sensor and data fusion. Perception supports algorithm processing.

The Future: Level 5 full automation

Localization and backend systems providing filtering, data mining and data provision capabilities to support E/E onboard system development.

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AUTOSAR Adaptive Platform – emerging from deeply embedded systems

Application framework

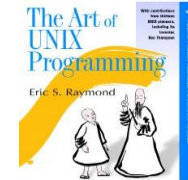
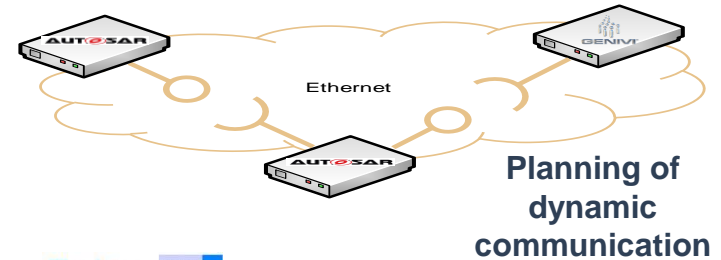
- Support for run-time configuration
- Service-oriented communication
- Partial update, system update and upgrade capabilities

Formats for design data

- Configuring of dynamic behavior (e.g. constraints for scheduling and communication)
- Consider automotive specific cooperation scenarios
- Support integration with existing systems (Classic Platform)

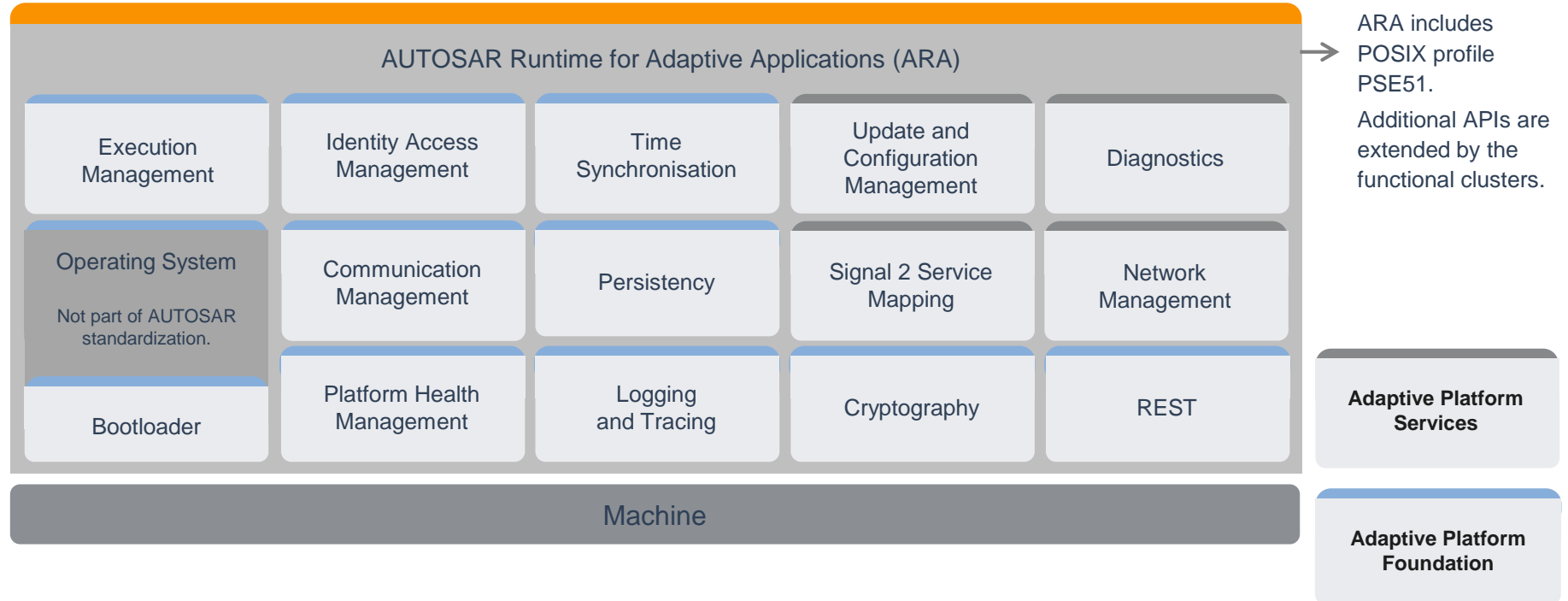
Reference architecture

- Reuse existing (non-automotive) standards
- Ease software development
- Support automotive use-cases and protocols
- Reference Implementation



... and many more

AUTOSAR runtime for adaptive applications – logical architecture



Classic Platform vs. Adaptive Platform

Technical characteristics



Based on OSEK

Execution of code directly from ROM

Same address space for all applications
(MPU support for safety)

Optimized for signal-based communication
(CAN, FlexRay)

Fixed task configuration

Specification



Based on POSIX

App. is loaded from persistent memory into RAM

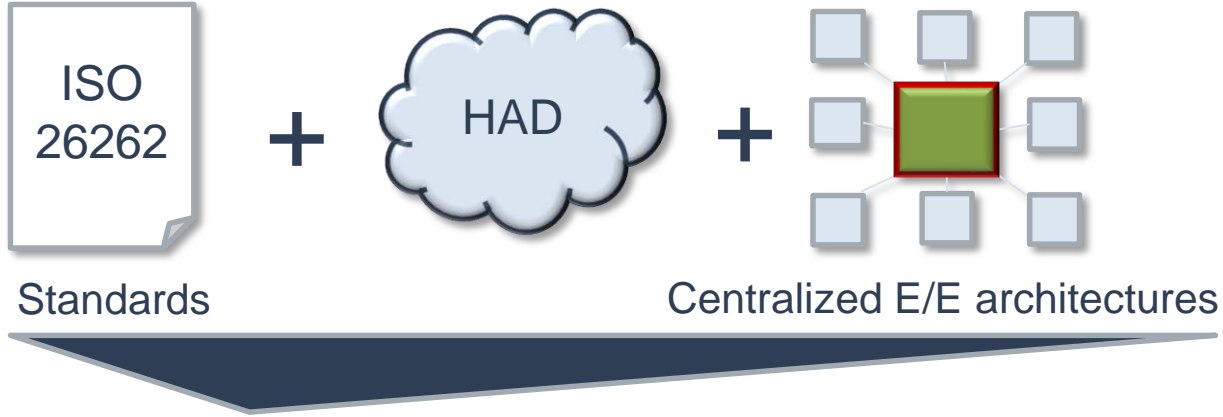
Each application has its own (virtual) address
space (MMU support)

Service-oriented communication

Support of multiple (dynamic) scheduling
strategies

Specification and code

Safety expectations, where do they come from?



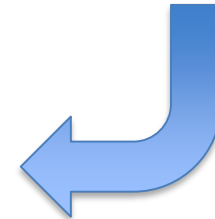
- **System architectures** capable up to ASIL D
- **Reliable system architectures**

Demand

- Separation
- Failure mitigation
- Freedom from interference
- ...

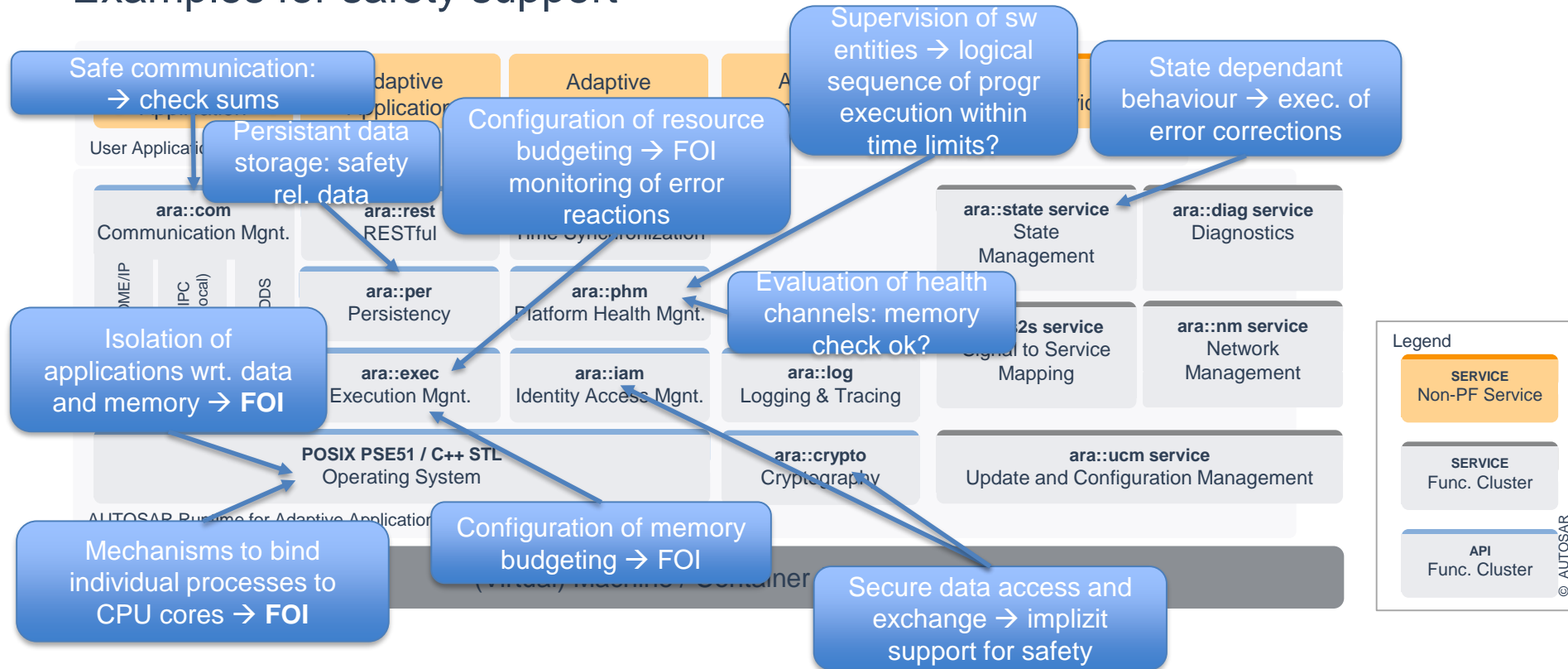
Supported by Autosar Adaptive Platform:

- Architectural decisions
- Features
- ...



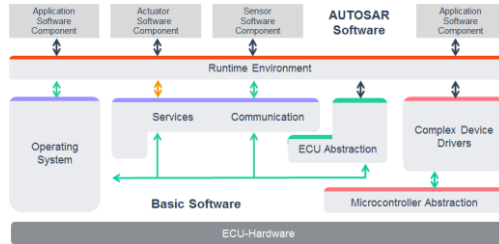
Features and architectural constraints

Examples for safety support



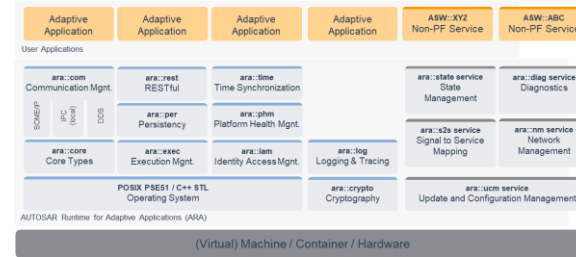
Safety approach

Classic Platform



- Definition of Safety mechanisms integrated into the Layered Architecture
- Possibility to tailor Safety mechanisms to project needs
- SEooC approach applicable

Adaptive Platform



- Definition of Safety mechanisms integrated into the service oriented approach
- Possibility to tailor Safety mechanisms to project needs
- Definition of the Platform Health Manager

➔ Interoperability between Classic and Adaptive Platform on bus level (e.g. E2E communication)

Security

- AUTOSAR goals
 - Support the development of secure systems through the two standards
 - To provide layered automotive security approach, to define measures at specific layers:
 - Individual ECU
 - In vehicle network
 - E/E architecture
 - Connected vehicle
 - Provide und support Coexistence and Interoperability of Security measures between CP and AP
- Adaptive Platform Security Feature Team
 - Responsible for providing features that enable the development of a secure system
 - Provide security controls to platform functional clusters and for secure deployment of adaptive platform application

Classic Platform vs. Adaptive Platform

Technical characteristics – additional security features



Classic Platform

Based on OSEK

Execution of code directly from ROM

Same address space for all applications (MPU support for safety)

Optimized for signal-based communication (CAN, FlexRay)

Fixed task configuration

Specification



Adaptive Platform

Based on POSIX

App. is loaded from persistent memory into RAM

Each application has its own (virtual) address space (MMU support)

Service-oriented communication

Support of multiple (dynamic) scheduling strategies

Specification and code

POSIX compliant OS security features

Applications must be authenticated

Individual process tree / no awareness of other processes

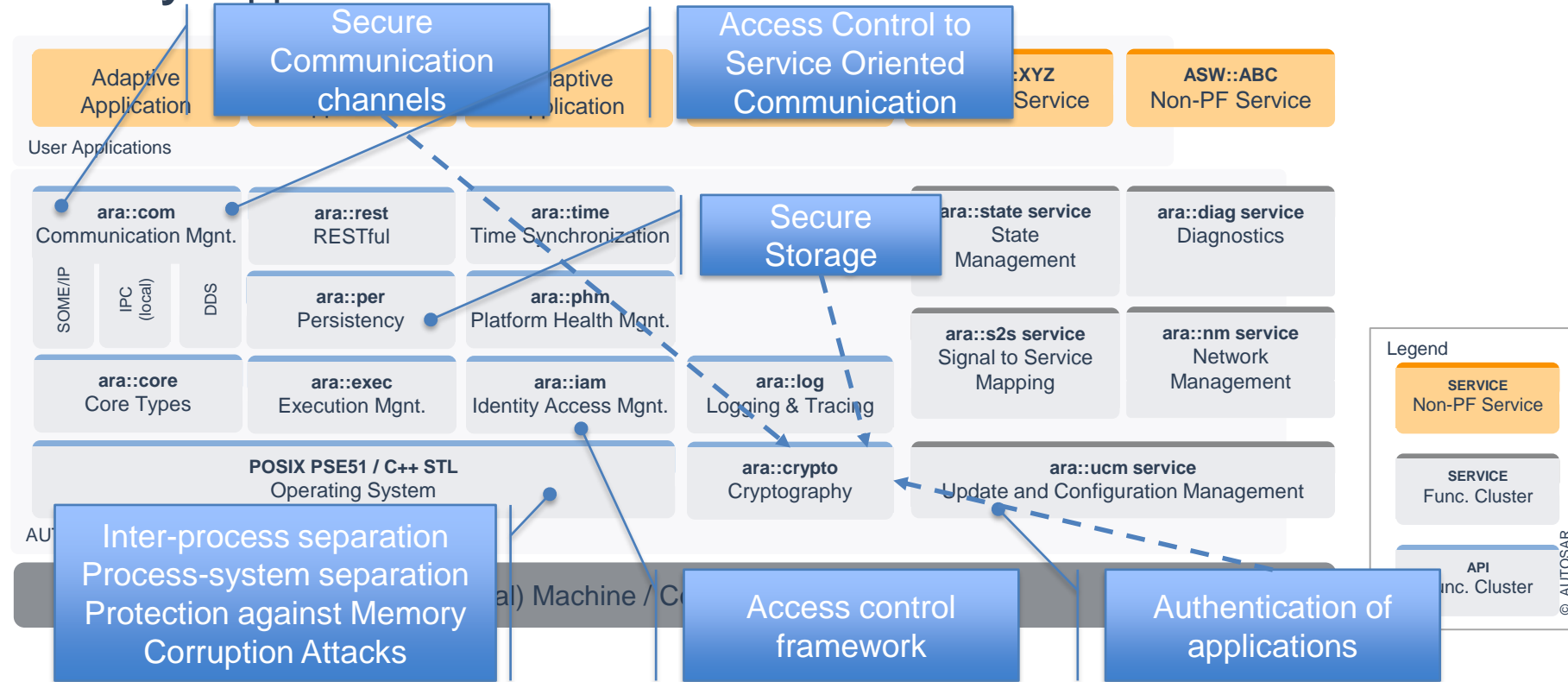
Secure communication channels (TLS, IPsec)
Access control to services

Predefined quota of memory allocation and fair distribution of processor time

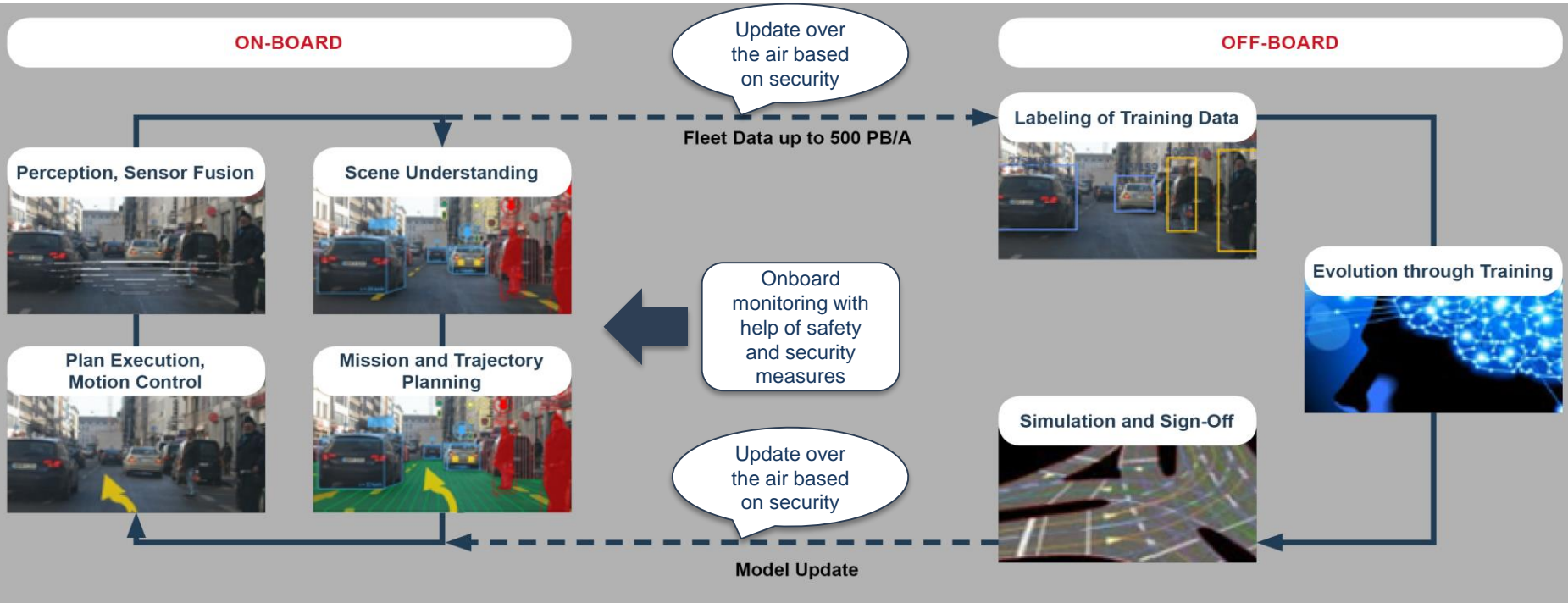


Features and architectural constraints

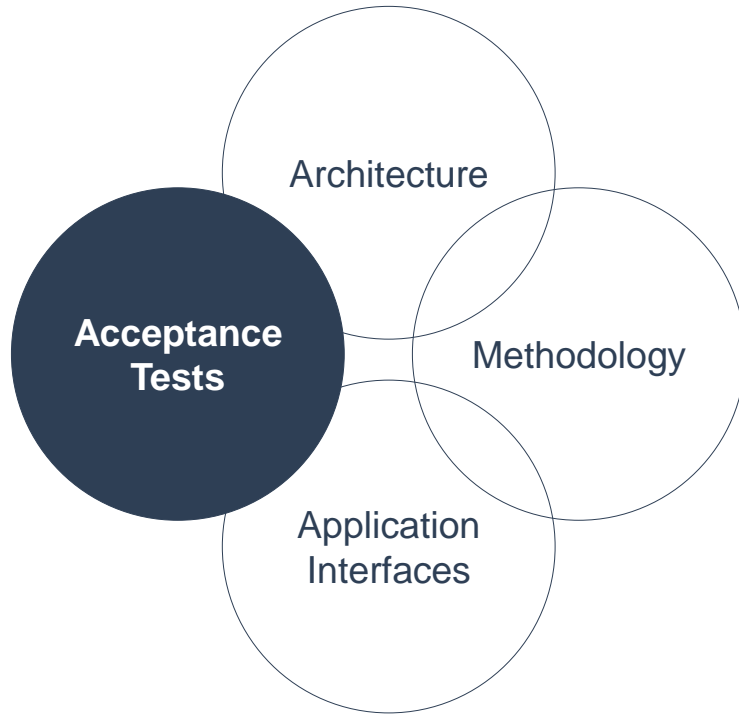
security support



Intelligence functionality within the vehicle should run on a trusted platform based on safety and security



TESTING

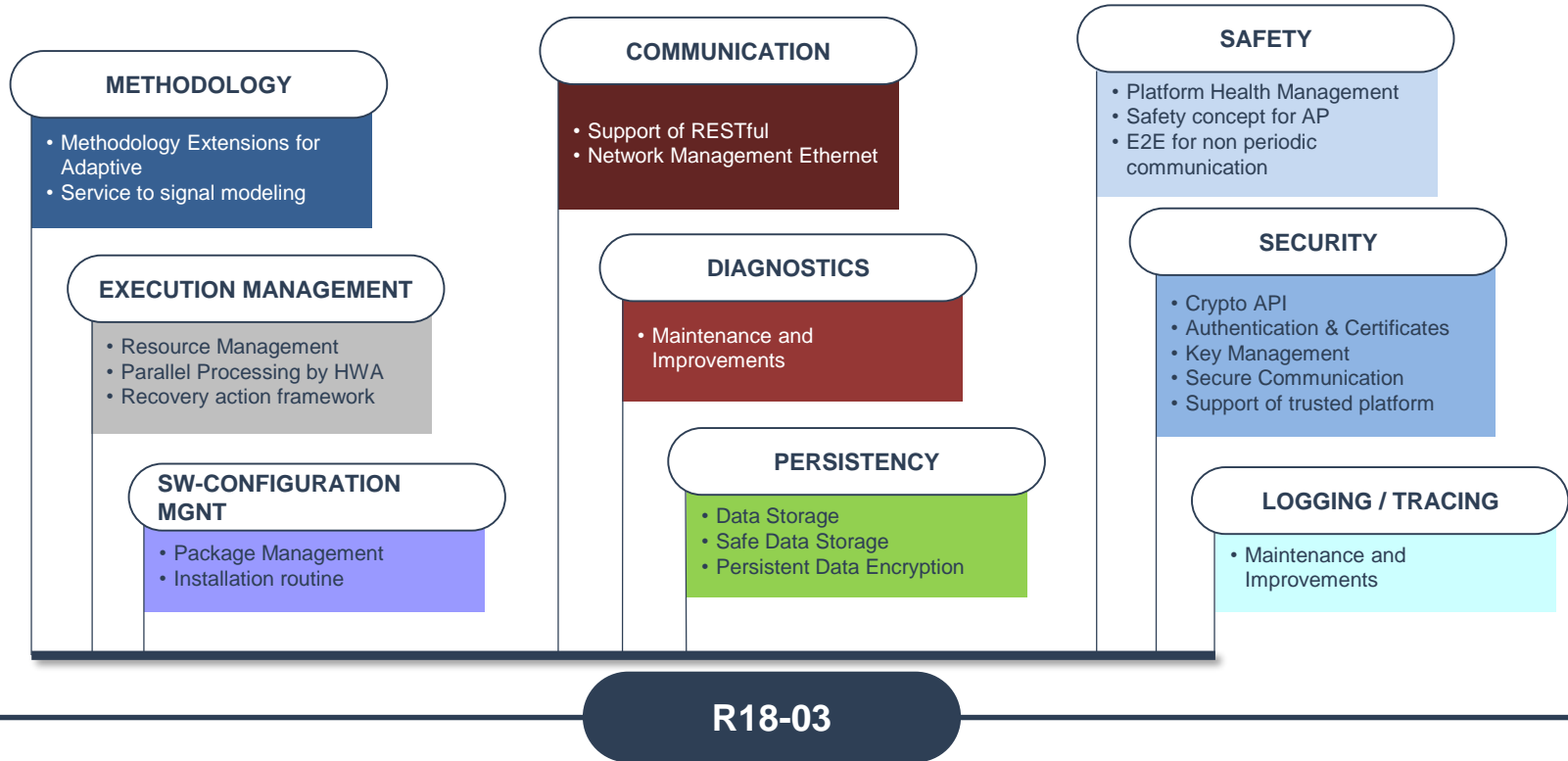


Specification of test cases intending to validate the behavior of an AUTOSAR implementation with AUTOSAR application software components or within one vehicle network.

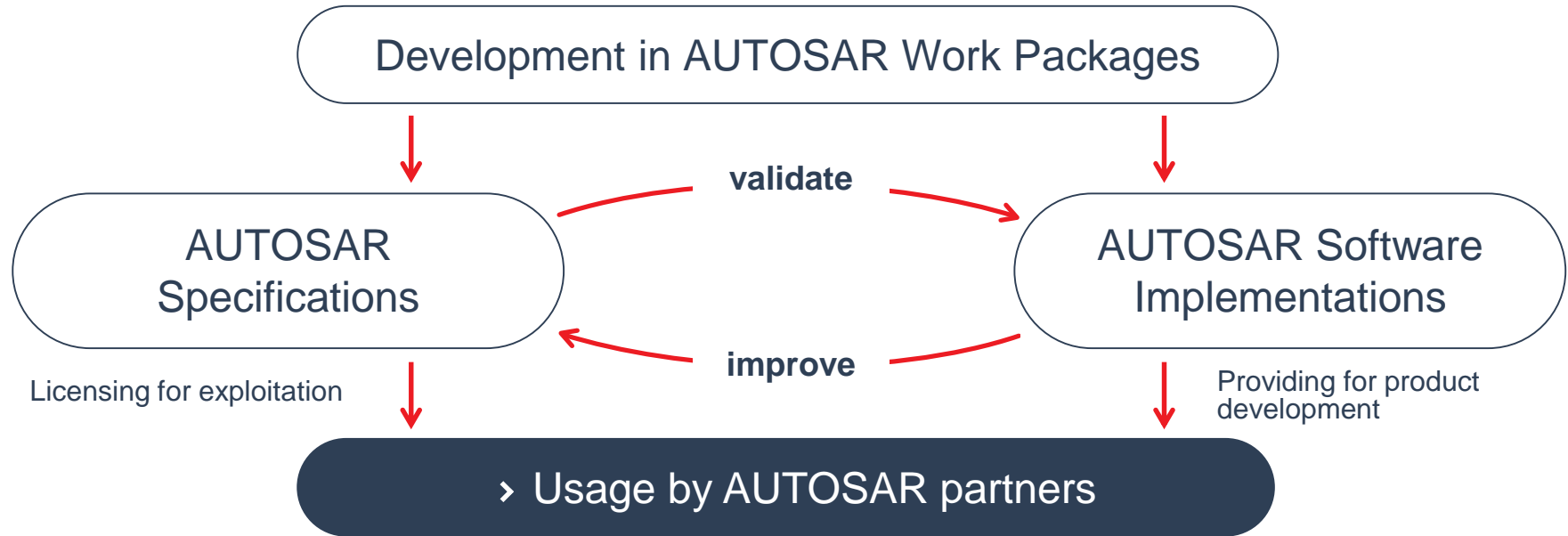
Verification & Validation

- AUTOSAR Platforms via Acceptance Tests are straight due to supplied test cases.
- AI input increases complexity because of non deterministic behaviour.
- UoA applications need to supply diagnostic functionality for safety by themselves w.r.t. required diagnostic coverage.
- V&V needs to be tailored to criticality, requirement maturity and complexity of application → Efficiency of V&V.

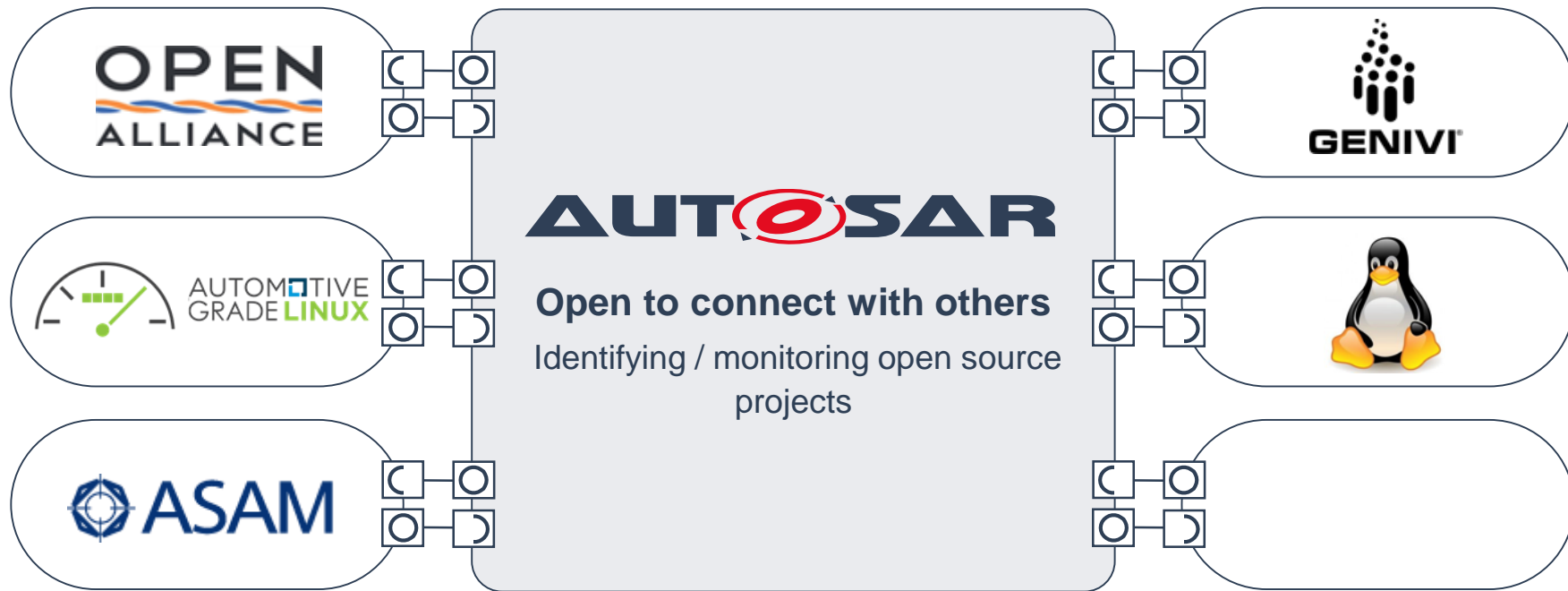
Features of Adaptive Platform Release 18-03.



Joint development of AUTOSAR specifications and exemplary software implementations for the AUTOSAR Adaptive Platform



Transparent to other standards



Topics

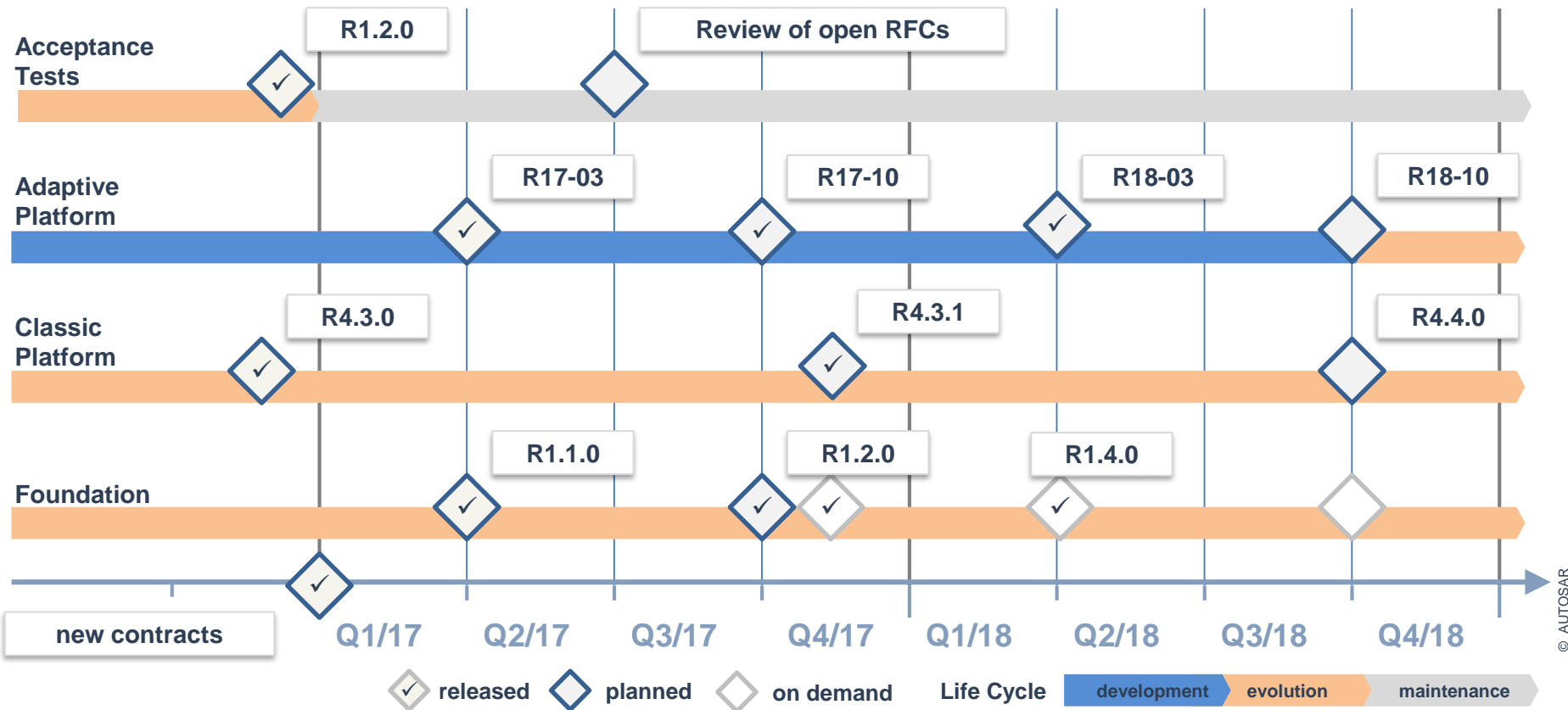
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AUTOSAR Platform Roadmap



The AUTOSAR Core Partners are fully committed to the standardization of the AUTOSAR Adaptive Platform

- Number-crunching algorithms and high interconnectivity are the demands of future technologies. The Adaptive Platform is exactly what we need.
- AUTOSAR is one of the key enablers for autonomous driving cars.
- AUTOSAR is our standard of choice for realizing new technologies such as autonomous driving and interconnectivity.



11th AUTOSAR



Open Conference and Networking Reception

Networking Reception

Tuesday,
November 6th, 2018
7:00 pm – 10:00 pm

+

Conference

Wednesday,
November 7th, 2018
All-day

Venue:

The Portman Ritz-Carlton Shanghai
1376 Nanjing Xi Lu, Shanghai 2000-40, China



Further information:

<https://www.autosar.org/news-events/>

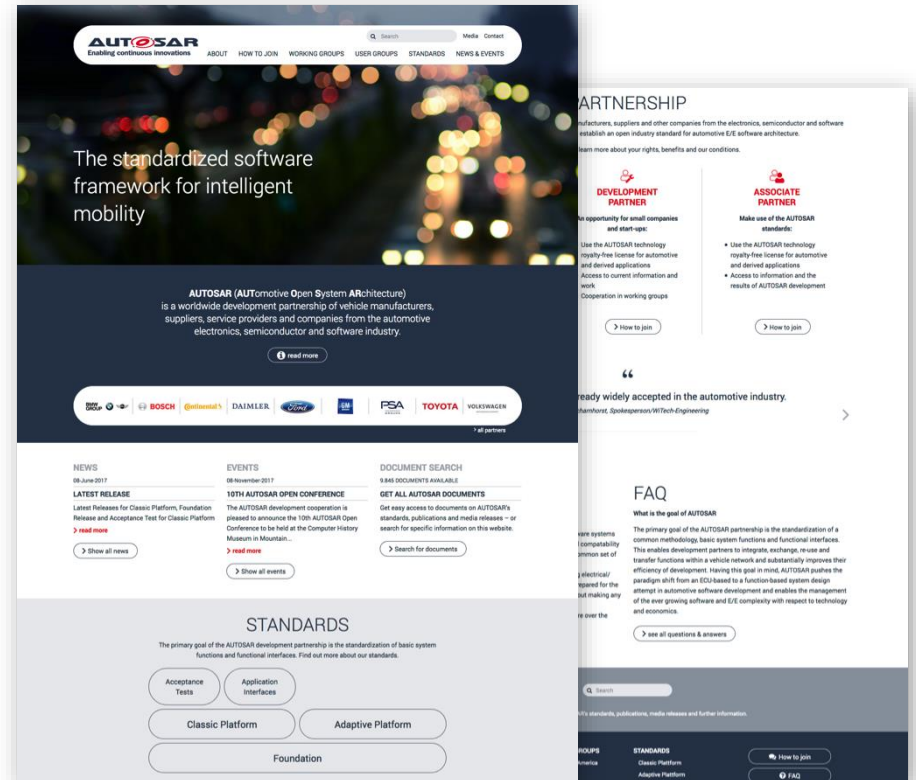


Further information on AUTOSAR

For more information on AUTOSAR:

- Working results
- User Experiences
- Exploitation

You are welcome to have a look at AUTOSAR's publications available at the AUTOSAR website www.autosar.org.



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