



A Tandem TerraSAR-X Configuration for Single-Pass Interferometry

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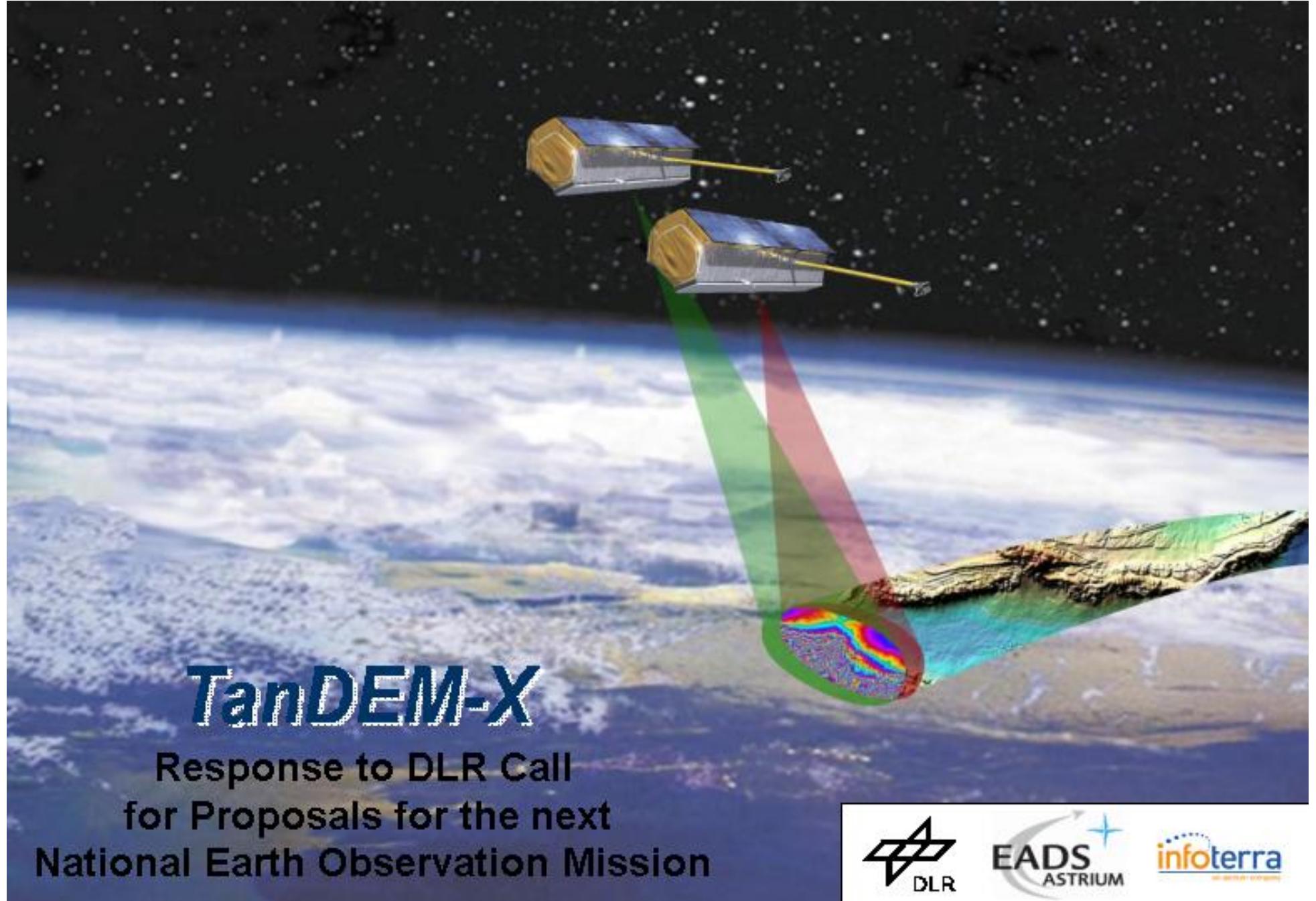
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TanDEM-X
Response to DLR Call
for Proposals for the next
National Earth Observation Mission



System and Mission Heritage



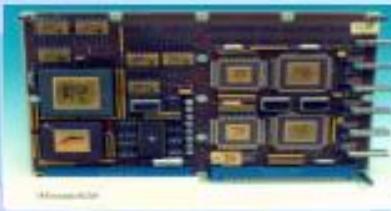
X-SAR



SRTM



DESA



TOPAS

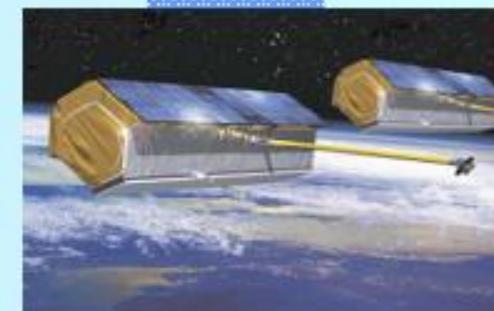
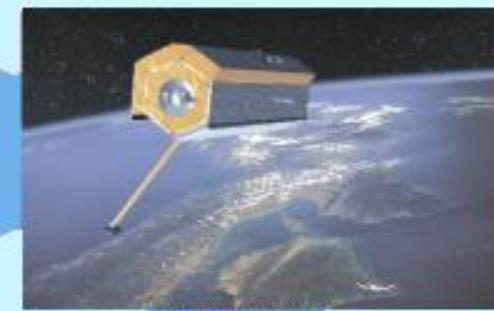


CHAMP



GRACE

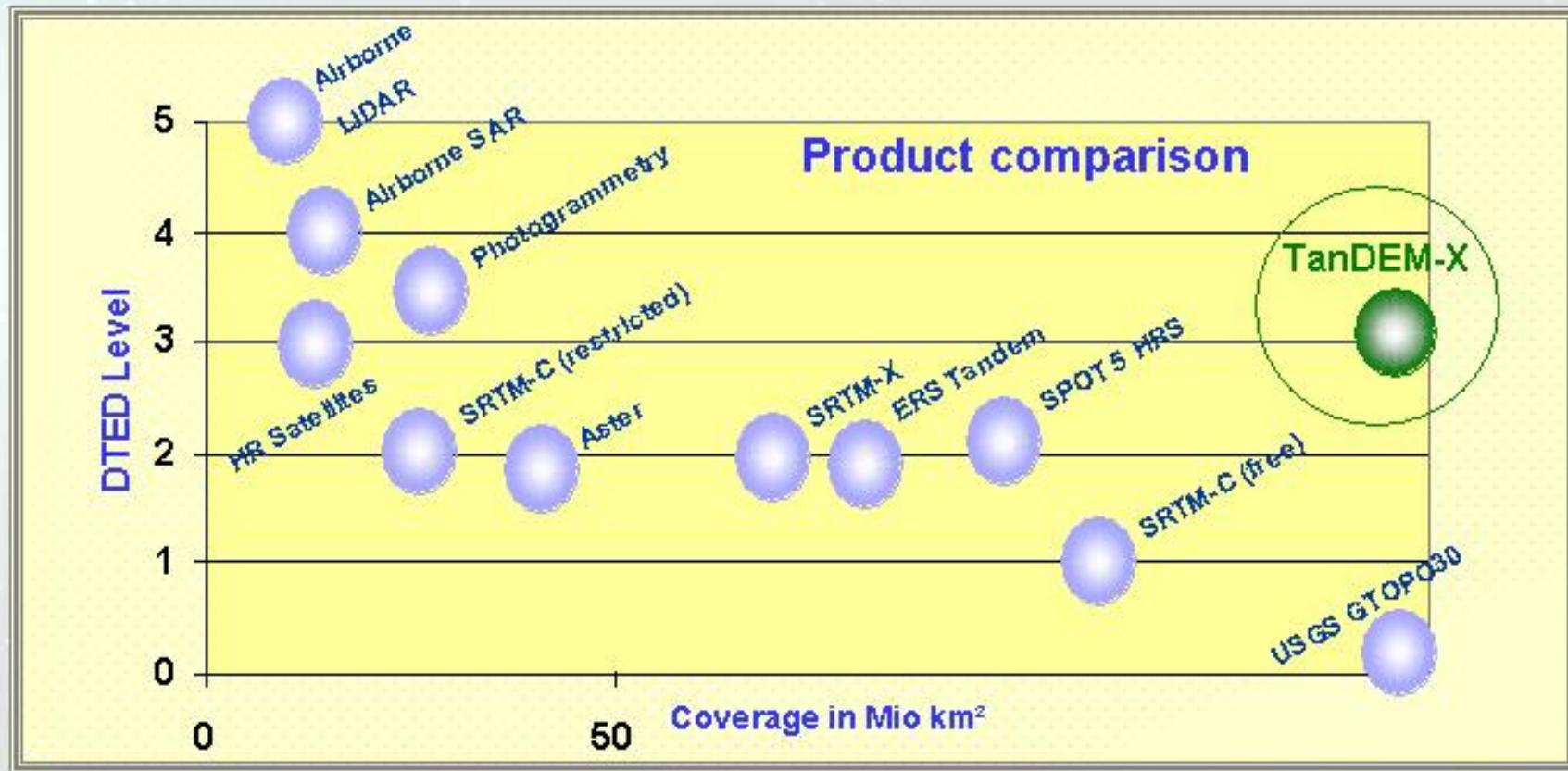
TerraSAR-X



TanDEM-X



TanDEM-X: Primary Mission Goal

**Primary Mission Goal:**

- DEM generation corresponding to HRTI-3 (DTED-3) standard with global coverage with minimum 3 years of nominal operation with TerraSAR-X

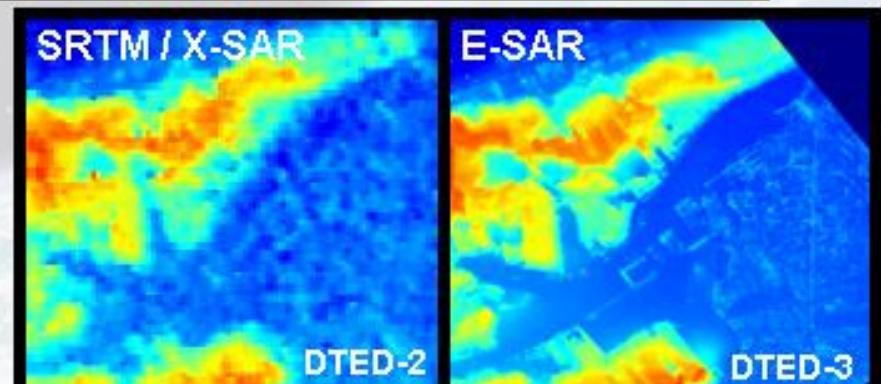


Interferometry with TanDEM-X



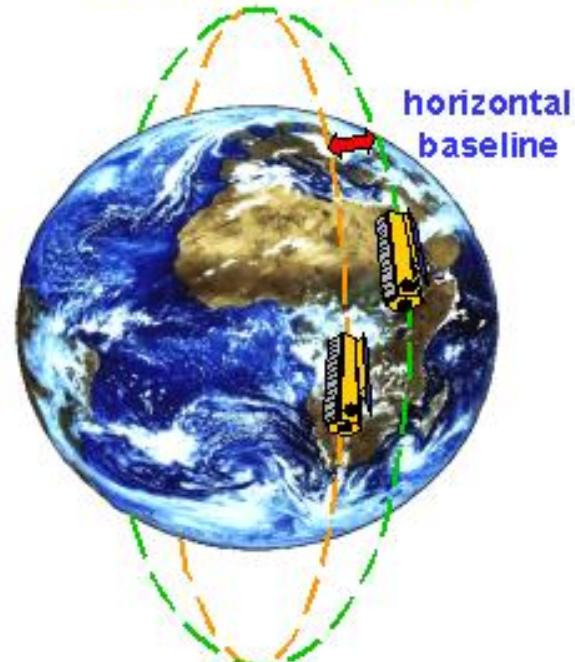
	Spatial Resolution	Absolute Vertical Accuracy (90%)	Relative Vertical Accuracy (90%)	Absolute Horizontal Accuracy (90% circ.)	Relative Horizontal Accuracy (90% circ.)
DTED-1	90m x 90m	< 16 m	< 10 m	< 60 m	< 45 m
DTED-2	30m x 30m	< 16 m	< 10 m	< 20 m	< 15 m
DTED-3 (HRTI-3)	10m x 10m	< 10 m	< 2 m (4m, slope>20 %)	< 10 m	< 3 m

Other product specifications will be considered during phase A with respect to users requirements



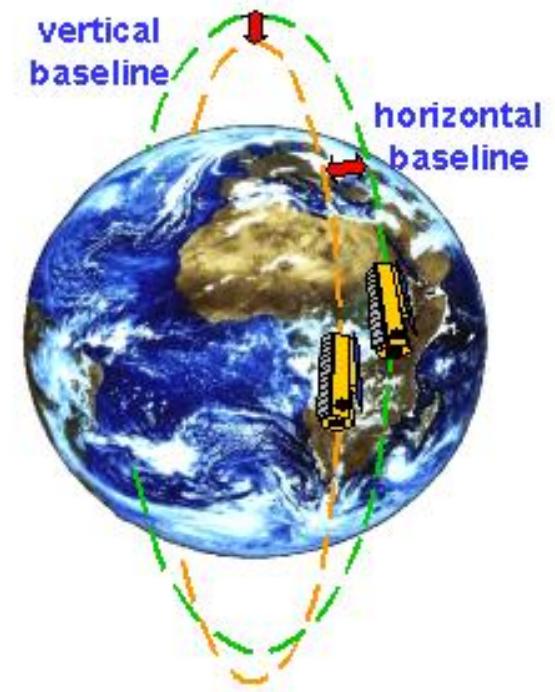
TanDEM-X: Orbit, Operation Modes and Performance

2SAT Pendulum



Digital Elevation Model (DEM)
from SRTM Mission

2SAT Helix

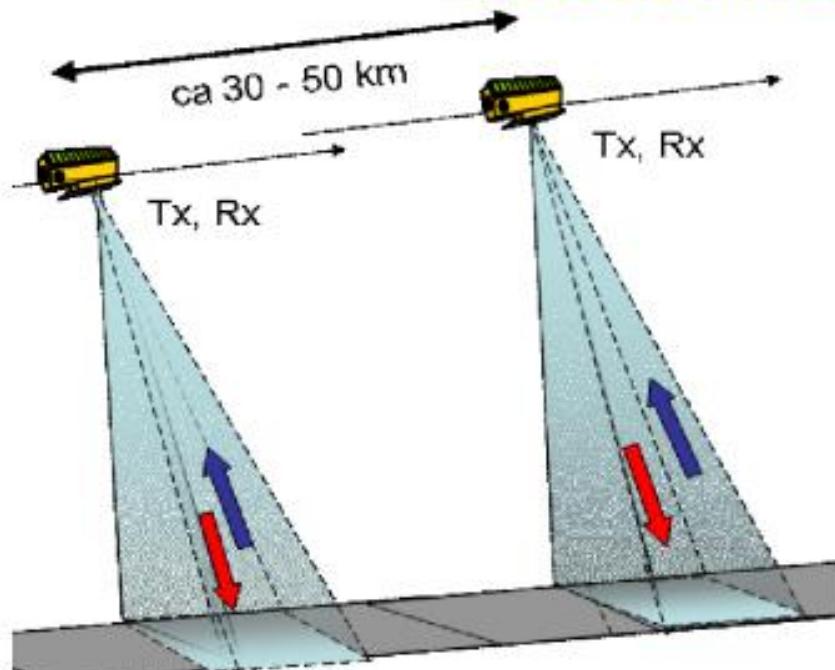


Single-Pass Cross-Track Interferometry with TerraSAR-X Tandem:

- no temporal surface decorrelation (as opposed to repeat-pass interferometry)
- almost no atmospheric distortions (as opposed to repeat-pass interferometry)
- large interferometric baselines

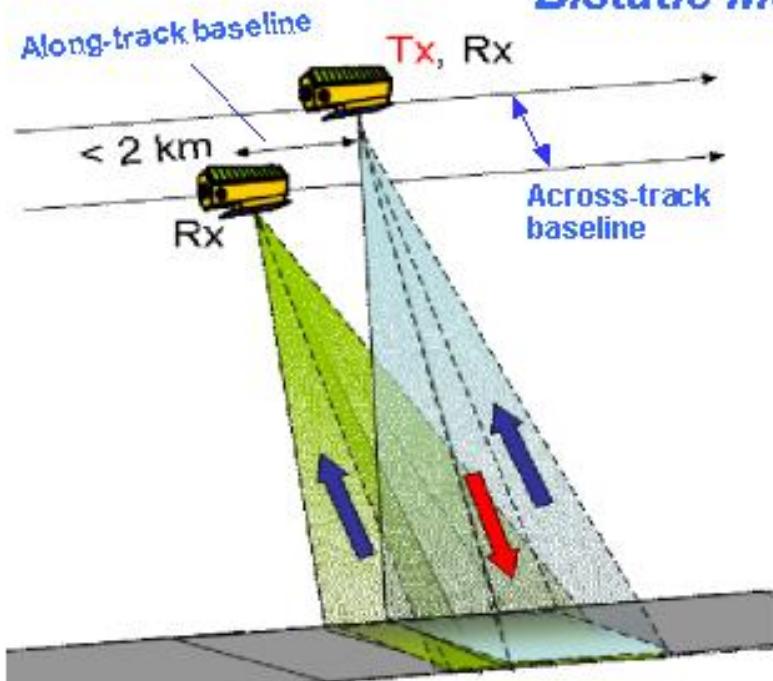


Monostatic Mode



- TerraSAR-X 1 and TanDEM-X transmit and receive independently
- Large along-track separation (> 30 km) to avoid interference
- Temporal decorrelation (~ 10 sec)
- Higher overall power consumption
- More stringent requirements with regard to orbit accuracy (smaller interferometric baselines)

Bistatic Mode



- Only TerraSAR-X 1 transmits (or only TanDEM-X transmits)
- TerraSAR-X 1 and TanDEM-X receive simultaneously
- Antenna footprints must overlap
- Along-track displacement has to be small (< 2 km) (to ensure overlapping Doppler spectra)
- More stringent requirements on oscillator stability



<p>Stripmap Mode</p> <p>Resolution: $3 \text{ m} \times 3 \text{ m}$ Scene Size: $100 \text{ km} \times 30 \text{ km}$</p>	<p>ScanSAR Mode</p> <p>Resolution: $16 \text{ m} \times 16 \text{ m}$ Scene Size: $100 \text{ km} \times 100 \text{ km}$</p>	<p>Spotlight Mode</p> <p>Resolution: $1 \text{ m} \times 1 \text{ m}$ ($2 \text{ m} \times 2 \text{ m}$) Scene Size: $5 \text{ km} \times 10 \text{ km}$ ($10 \text{ km} \times 10 \text{ km}$)</p>

- Incidence angle range from 15° to 60°
- Dual polarisation data acquisition in all operational modes
- 300 MHz experimental mode with 0.5 m slant range resolution (1 m ground range @ 30 deg. incidence angle)
- Further experimental modes with Dual Receiving Antenna configuration (full polarimetric and along-track interferometry)

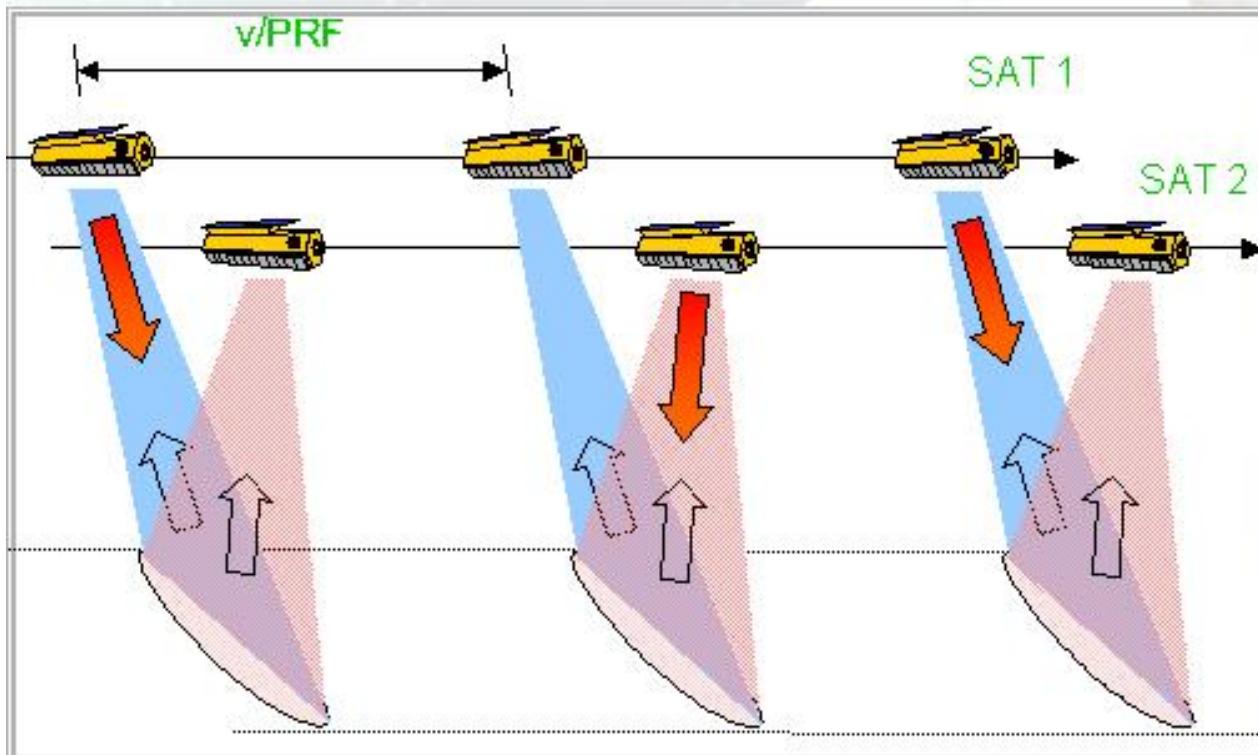
Bistatic Mode with Alternating Transmitters



Three interferograms with two “effective baselines”:

$$B_{\text{monostatic}} = 2 \cdot B_{\text{bistatic}}$$

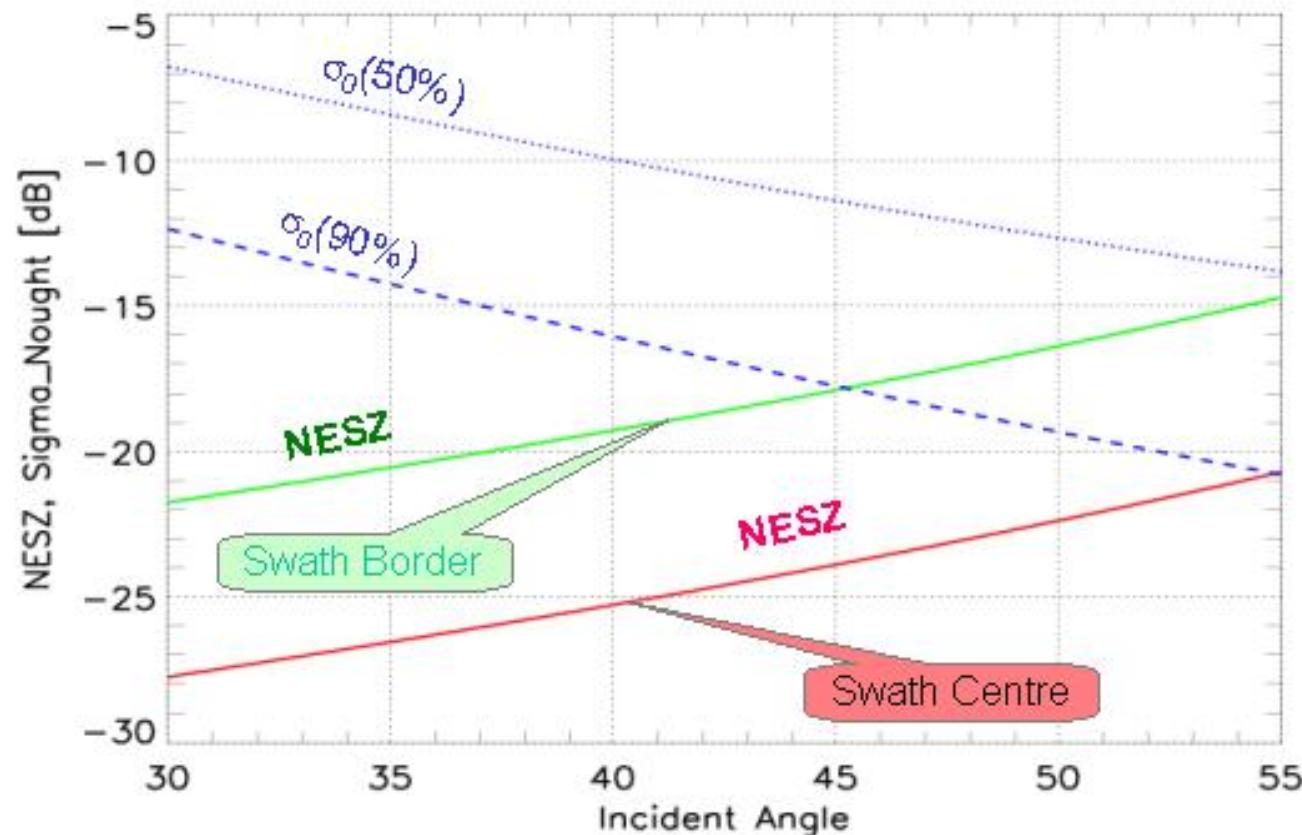
- + good height accuracy
(use large monostatic baseline)
- + improved phase unwrapping
(use smaller bistatic baselines)
- + phase synchronization possible
- requires increased PRF
(as in polarimetric mode)



$$\left. \frac{\partial \varphi}{\partial h} \right|_{\text{monostatic}} = 2 \cdot \left. \frac{\partial \varphi}{\partial h} \right|_{\text{bistatic}}$$

Noise Equivalent Sigma Zero

$$\text{Noise Equivalent Sigma Zero} = \frac{4^4 \pi^3 r_{Tx}^2 r_{Rx}^2 v \sin(\Theta_i) k TBF}{P_{Tx} G_{Tx} G_{Rx} \lambda^3 c_0 \tau PRF}$$



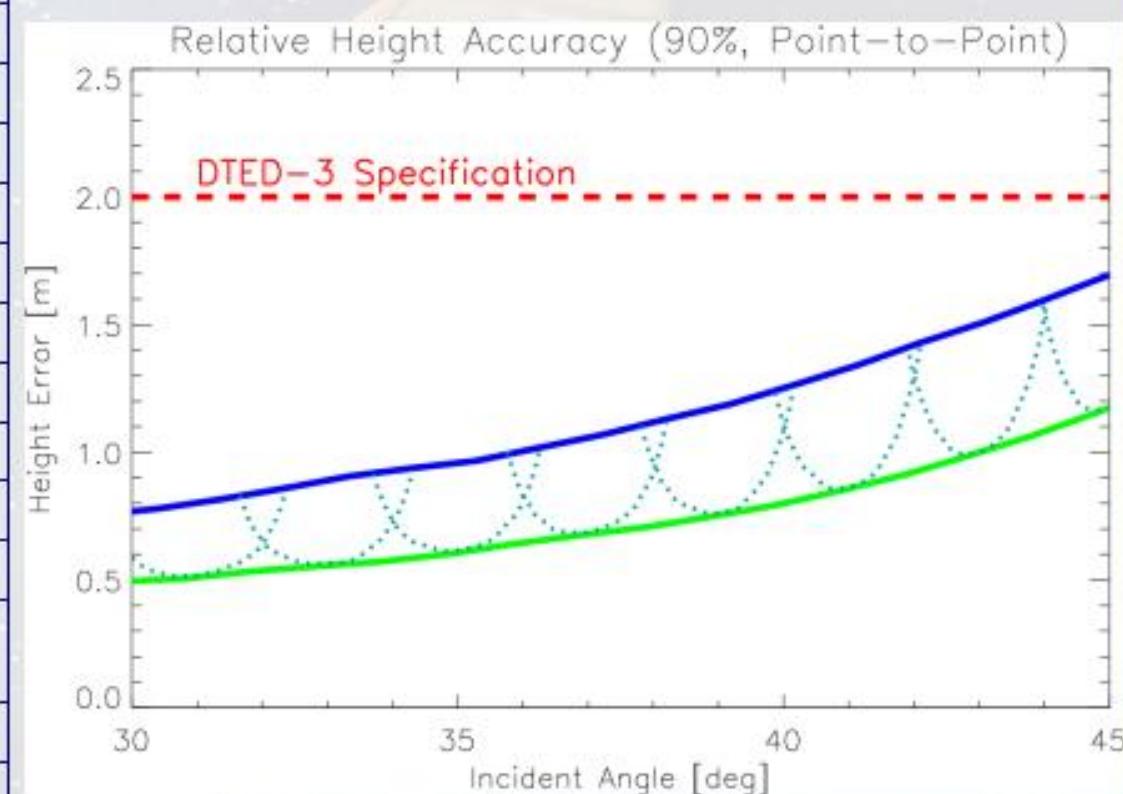
Assumptions:

- no antenna tapering for small incident angles
- swath width: 30km
- 6dB losses at swath border

Interferometric Performance Estimation



Parameter	Value	Relative Height Accuracy
Wavelength	0.031 m	
Chirp Bandwidth	100 MHz	
Peak Transmit Power	2260 W	
Duty Cycle	18 %	
Noise Figure	4.5 dB	
Atmospheric Losses	0.5 dB	
Antenna Size (Tx , Rx)	4.8 m x 0.7 m	
PRF	3500 Hz	
Processed Bandwidth	2300 Hz	
Co-Registration Accuracy	1/10 pixel	
Quantization	3 bit (BAQ)	
Sigma Nought Model (90 % occurrence levels)	Ulaby (X-Band, HH, Soil)	
Effective Baseline	1 km	
Along-Track Displacement	1 km	
Swath Width	30 km	
Post Spacing	12 m x 12 m	



The graph shows Height Error [m] on the Y-axis (0.0 to 2.5) versus Incident Angle [deg] on the X-axis (30 to 45). A red dashed horizontal line at 2.0 m represents the DTED-3 Specification. Three curves are plotted: a solid blue line, a dotted green line, and a dotted cyan line. All three curves start at approximately 0.8 m at 30 degrees and increase monotonically as the incident angle increases. The solid blue curve is the highest, followed by the dotted green curve, and then the dotted cyan curve.

Incident Angle [deg]	Height Error [m] (Blue Solid)	Height Error [m] (Green Dotted)	Height Error [m] (Cyan Dotted)
30	0.8	0.5	0.5
35	1.0	0.6	0.6
40	1.3	0.8	0.8
45	1.7	1.2	1.5

TanDEM-X Mission: Scientific Exploration

Applications derived from across-track interferometry

– Land Environment

Topographic Mapping, Cartography, Urban Areas, Disaster and Crisis Management, Navigation, Archaeology, Change Detection

– Hydrology

Ice and Snow, Wetlands, Morphology, Flooding

– Renewable Resources

Land use mapping, agriculture, forestry and grassland

– Oceanography

Wind and Waves, Ocean Dynamics, Ship Detection, Bathymetry

– Geology

Geological mapping, Earthquake /Tectonics, Volcanoes, Landslides

Applications with Along-Track Interferometry

- | | |
|--|--|
| <ul style="list-style-type: none">– <i>Oceanography</i>– <i>Traffic</i>– <i>Glaciology</i> | <p><i>Ocean currents, coastal zone mapping</i></p> <p><i>Traffic flow monitoring</i></p> <p><i>Ice flow monitoring</i></p> |
|--|--|

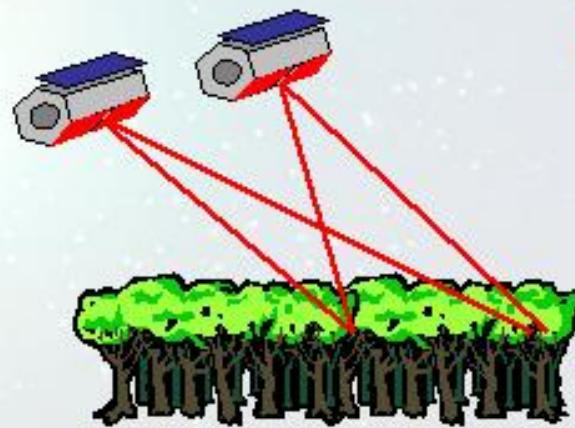
New Techniques

- | | |
|---|---|
| <ul style="list-style-type: none">– <i>Pol-InSAR</i>– <i>Digital beamforming</i>– <i>Multi-Angle Observations</i> | <ul style="list-style-type: none">– <i>Bi-static Processing</i>– <i>Super Resolution</i>– <i>Formation Flying</i> |
|---|---|



Pol-InSAR

Pol-InSAR



Observables

3 Interferometric Coherences

3 Interferometric Phases

for one baseline and three polarisation states

I Step:
Model and Validation Development

Coherent Scattering Model

Natural Scatterers



Forest Parameters



Surface Parameters

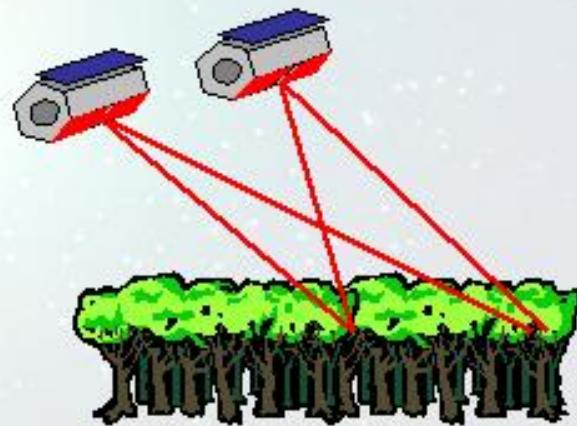


Agricultural Parameters



Land Ice Parameters

Pol-InSAR



Observables

3 Interferometric Coherences

3 Interferometric Phases

for one baseline and three polarisation states

II Step: Model and Validation Inversion

Coherent Scattering Model

Natural Scatterers



Forest Parameters



Surface Parameters



Agricultural Parameters



Land Ice Parameters

L-band (PoI-InSAR)



Baseline=15m



HH



HV



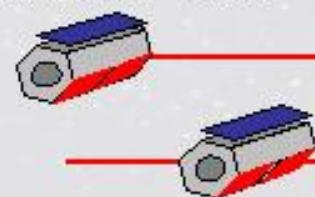
VV



L-band (PoInSAR)



Baseline=15m



HH-HH



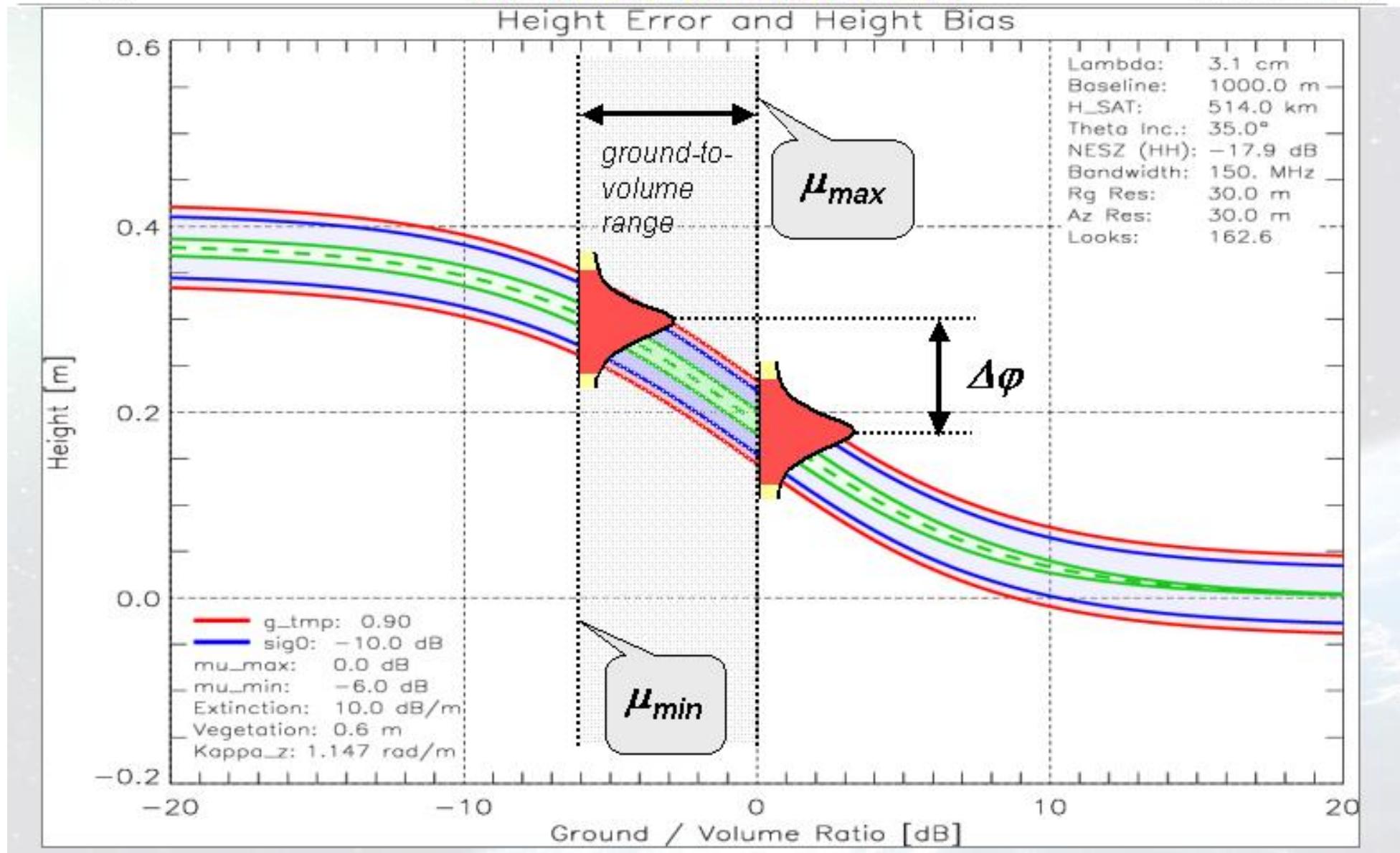
HV-HV



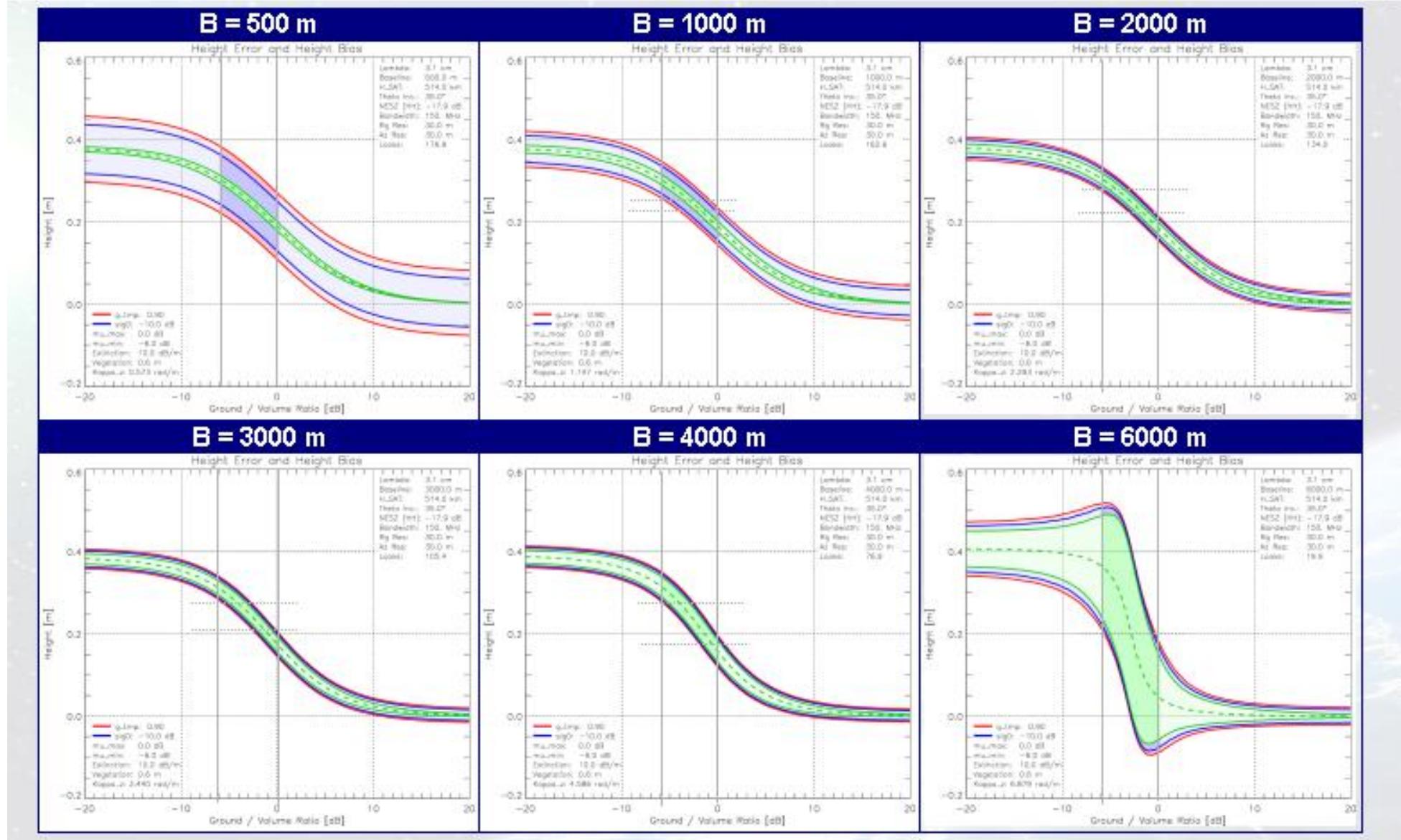
VV-VV

E-SAR / Test Site: Oberpfaffenhoffen

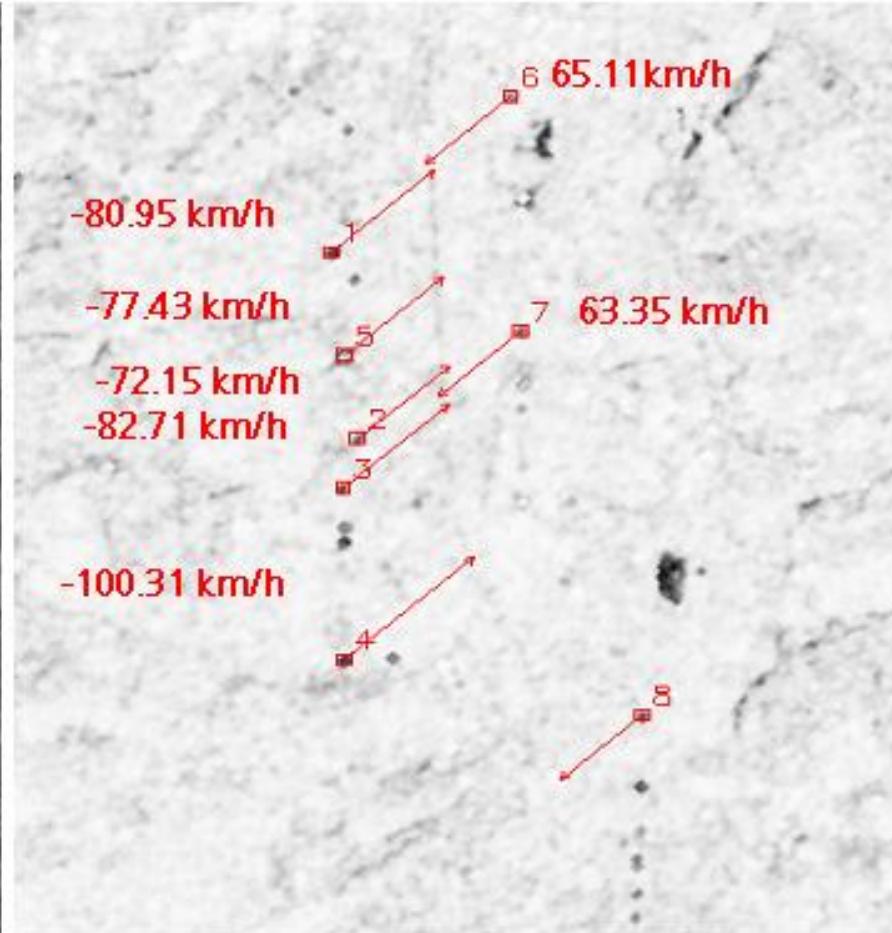
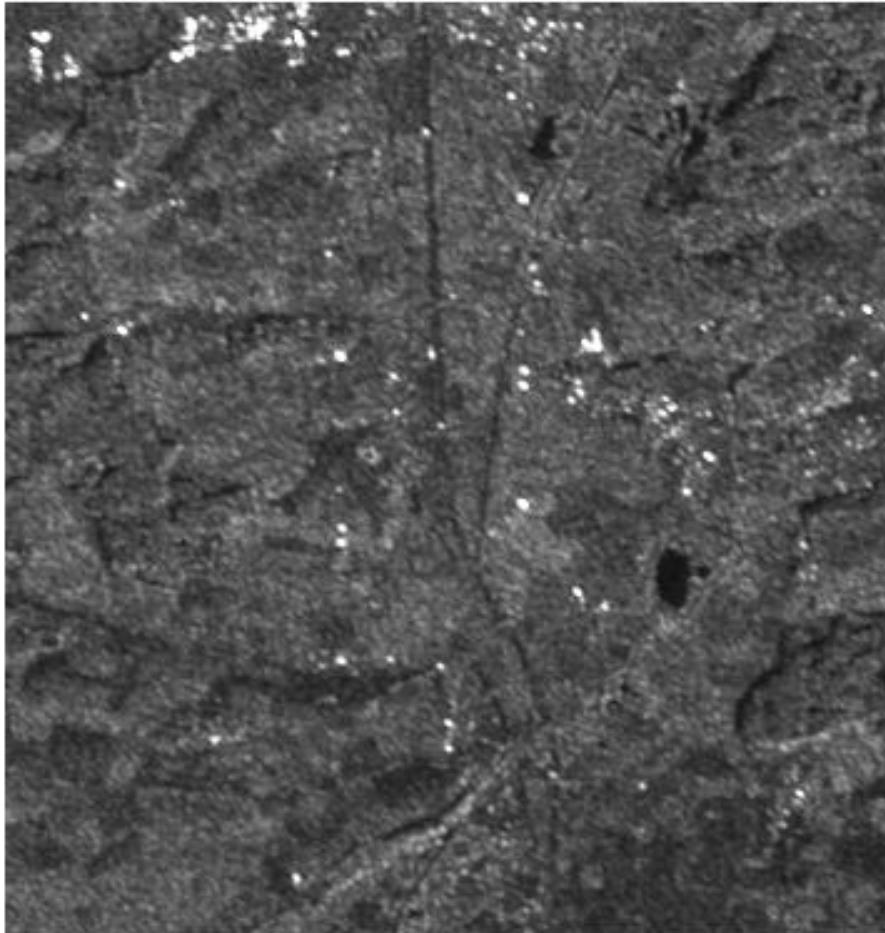
Polarimetric Interferometric: Performance Estimation



Polarimetric Interferometry: Performance Estimation

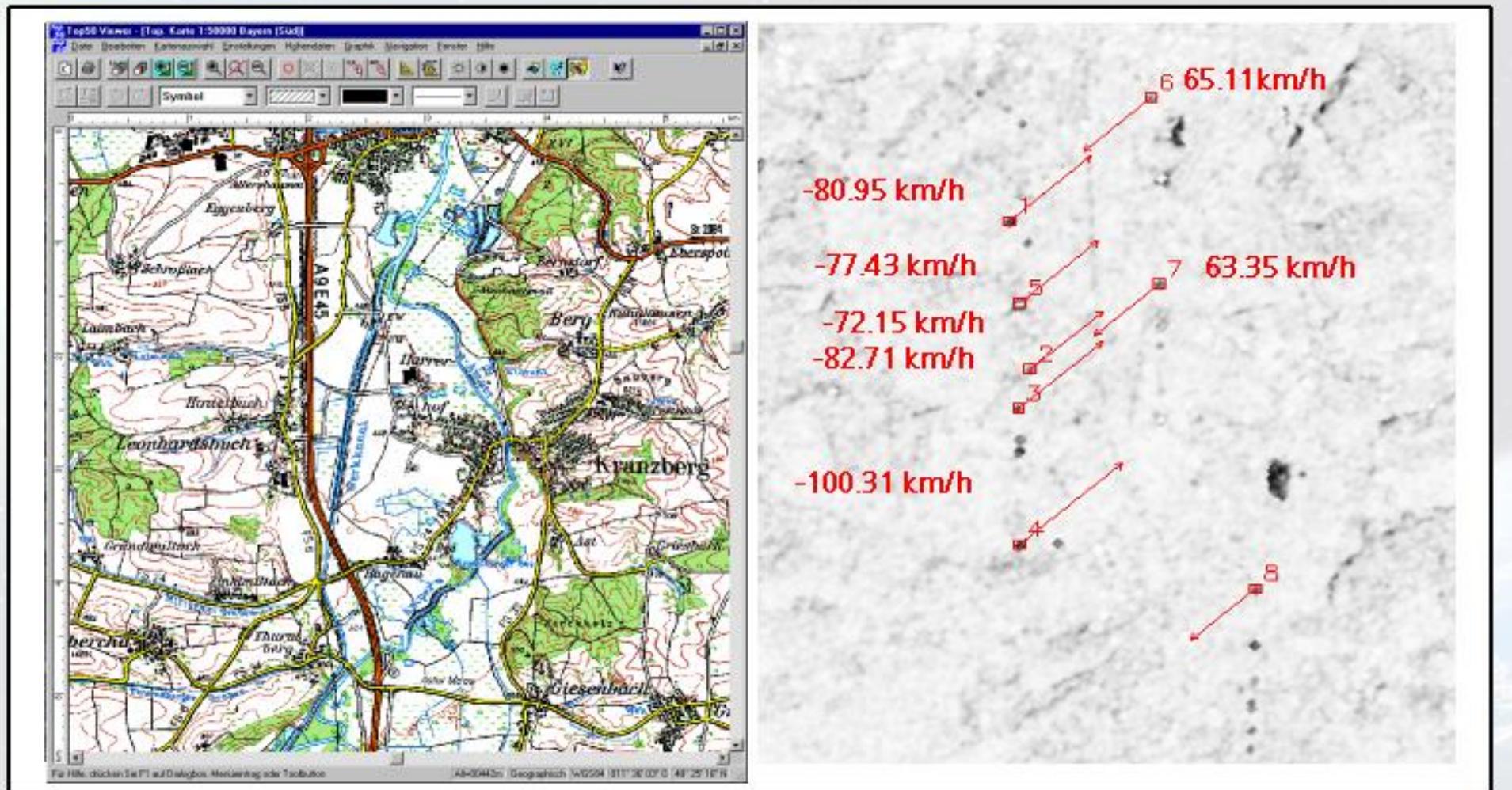


Along-Track Interferometry



SRTM/X-SAR data from the highway A-9 (7 meters along-track displacement, DLR-IMF)

Traffic Monitoring with Along Track Interferometry

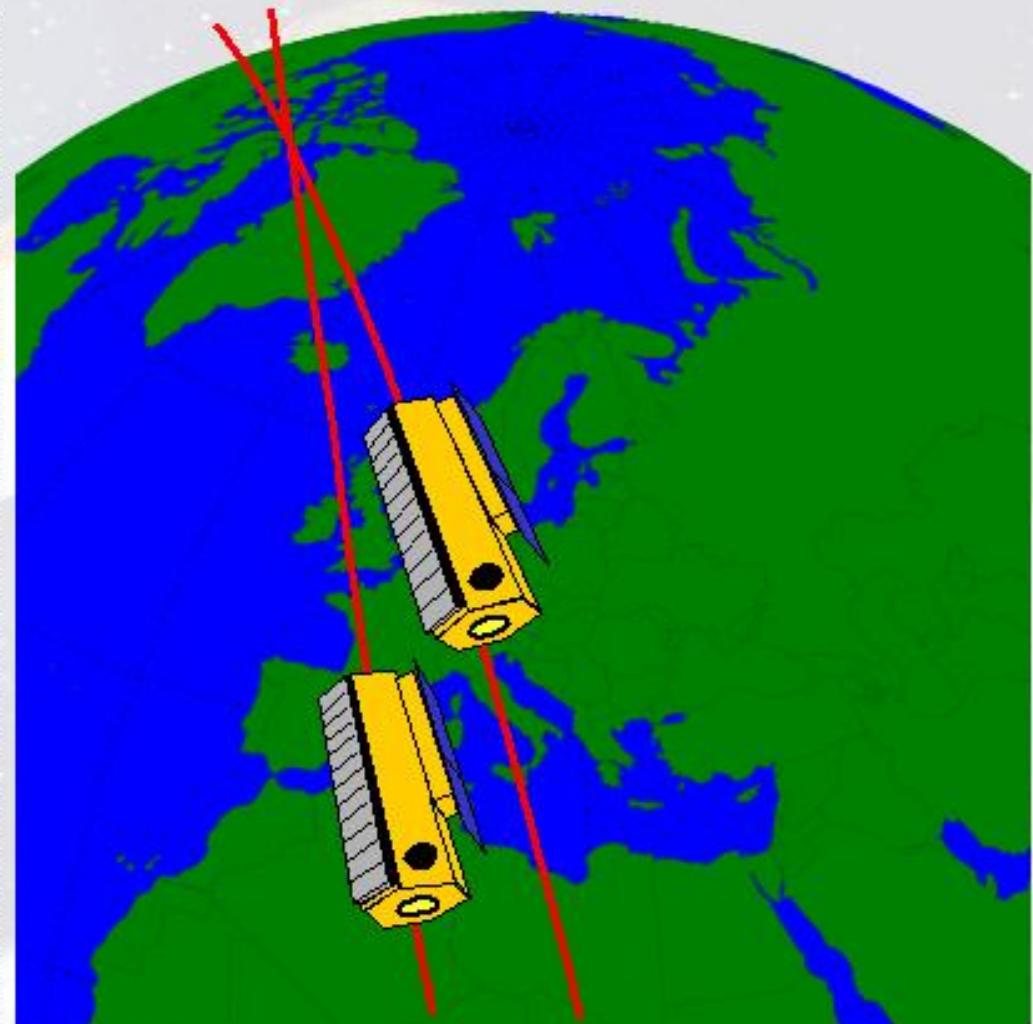


SRTM/X-SAR data from the highway A-9 (7 meters along-track displacement, DLR-IMF)

Summary

Scientific Opportunities

- **DEM-based applications (DTED-3):**
 - *land environment, hydrology, geology, etc.*
- **polarimetric SAR interferometry**
- **along-track interferometry**
(e.g. mapping of ocean currents, moving target indication)
- **super-resolution in azimuth and range**
- **Digital beam-forming with 4 phase centers**
- **multi-angle bistatic observations**
- **bi-static SAR polarimetry**
- **stereogrammetric applications**
- **Formation flying**



Main challenges to be investigated in Phase A:

- *PRF and Phase Synchronisation (design upgrade)*
- *Precise baseline determination using differential GPS and phase measurements*
- *Close formation flying capability*
- *Bi-static and interferometric data processing (DTED-3)*
- *Spotlight SAR interferometry*
- *Interferometric calibration (Ocean data takes, tie points)*
- *Scientific applications and opportunities*